CPC COOPERATIVE PATENT CLASSIFICATION

F MECHANICAL ENGINEERING; LIGHTING; HEATING; WEAPONS; BLASTING (NOTE omitted)

ENGINEERING IN GENERAL

F15 FLUID-PRESSURE ACTUATORS; HYDRAULICS OR PNEUMATICS IN GENERAL

F15B SYSTEMS ACTING BY MEANS OF FLUIDS IN GENERAL; FLUID-PRESSURE ACTUATORS, e.g. SERVOMOTORS; DETAILS OF FLUID-PRESSURE SYSTEMS, NOT OTHERWISE PROVIDED FOR

NOTE

- In this subclass, the following terms are used with the meaning stated:
- "Telemotor" means a system or device in which a substantially constant amount of fluid is trapped between an input member and an output member to act as a fluid link;
- "Servomotor" means a fluid-pressure actuator, e.g. a piston and cylinder, directly controlled by a valve or other device which is responsive to operation of an initial controlling member; "Servomotor" does not cover a telemotor. The initial controlling member may be adjacent to the servomotor or at a distance, and may be, for example a hand lever.

1/00	Installations or systems with accumulators; Supply reservoir or sump assemblies
1/02	• Installations or systems with accumulators
1/021	• {used for damping}
1/022	 {used as an emergency power source, e.g. in case of pump failure}
1/024	 {used as a supplementary power source, e.g. to store energy in idle periods to balance pump load}
1/025	• • {used for thermal compensation, e.g. to collect expanded fluid and to return it to the system as the system fluid cools down}
1/027	• • having accumulator charging devices
1/0275	• • • {with two or more pilot valves, e.g. for
	independent setting of the cut-in and cut-out pressures}
1/033	with electrical control means
1/04	Accumulators
1/045	• • • {Dead weight accumulators}
1/08	• • • using a gas cushion; Gas charging devices; Indicators or floats therefor
1/083	•••• {the accumulator having a fusible plug}
1/086	•••• { the gas cushion being entirely enclosed by the separating means, e.g. foam or gas-filled balls }
1/10	• • • with flexible separating means
1/103	• • • • {the separating means being bellows}
1/106	• • • • {characterised by the way housing components are assembled}
1/12	• • • • attached at their periphery (flexible separating means in the form of a tube F15B 1/16)
1/125	••••• {characterised by the attachment means (F15B 1/14 takes precedence)}
1/14	•••• by means of a rigid annular supporting member
1/16	• • • • in the form of a tube
1/165	••••• {in the form of a bladder}
1/18	Anti-extrusion means

1/20 1/22 1/24 1/26 1/265	 fixed to the separating means Liquid port constructions with rigid separating means, e.g. pistons Supply reservoir or sump assemblies {with pressurised main reservoir}
3/00	Intensifiers or fluid-pressure converters, e.g. pressure exchangers; Conveying pressure from one fluid system to another, without contact between the fluids {(fluid-driven pumps F04B 9/08)}
5/00	Transducers converting variations of physical quantities, e.g. expressed by variations in positions of members, into fluid-pressure variations or <u>vice versa</u> ; Varying fluid pressure as a function of variations of a plurality of fluid pressures or variations of other quantities (F15B 9/00 takes precedence)
5/003	 {characterised by variation of the pressure in a nozzle or the like, e.g. nozzle-flapper system}
5/006	• {with electrical means, e.g. electropneumatic transducer (F15B 5/003 takes precedence)}

<u>Fluid-pressure actuator systems</u> (systems peculiar to the control of a particular machine or apparatus covered in a single other class, see the class for such machine or apparatus)

NOTE

This heading relates to moving members into one or more definite positions by means of fluid pressure. Pump, motor and control features so far as not peculiar to this purpose are classified in the relevant classes.

7/00	Systems in which the movement produced is definitely related to the output of a volumetric pump; Telemotors
7/001	• {With multiple inputs, e.g. for dual control}
7/003	• {with multiple outputs}
7/005	• {With rotary or crank input}
7/006	• • {Rotary pump input}
7/008	{with rotary output}

7/008 . {with rotary output}

7/02	• Systems with continuously-operating input and
	output apparatus
7/04	• In which the ratio between pump stroke and motor stroke varies with the resistance against the motor
7/06	• Details (F15B 15/00 takes precedence)
7/08	• Input units; Master units
7/10	• Compensation of the liquid content in a system (<u>F15B 7/08</u> takes precedence)
9/00	Servomotors with follow-up action, {e.g. obtained
	by feed-back control,} i.e. in which the position of
	the actuated member conforms with that of the
	controlling member
9/02	• with servomotors of the reciprocatable or
	oscillatable type
9/03	• • with electrical control means {(F15B 9/07,
	<u>F15B 9/09</u> , <u>F15B 9/17</u> take precedence)}
9/04	• • controlled by varying the output of a pump with
	variable capacity
9/06	• • controlled by means using a fluid jet
9/07	with electrical control means
9/08	• controlled by valves affecting the fluid feed or the
	fluid outlet of the servomotor ($F15B 9/06$ takes precedence)
9/09	• • • with electrical control means
9/09 9/10	in which the controlling element and the
9/10	servomotor each controls a separate member,
	these members influencing different fluid
	passages or the same passage
9/12	in which both the controlling element and
	the servomotor control the same member
	influencing a fluid passage and are connected
	to that member by means of a differential
	gearing
9/14	• with rotary servomotors
9/16	Systems essentially having two or more interacting
	servomotors {, e.g. multi-stage (F15B 18/00,
	<u>F15B 20/00</u> take precedence)}
9/17	• • with electrical control means

11/00	Servomotor systems without provision for follow- up action; {Circuits therefor}(<u>F15B 3/00</u> takes
	precedence)
11/003	• {Systems with load-holding valves}
11/006	• {Hydraulic "Wheatstone bridge" circuits, i.e. with four nodes, P-A-T-B, and on-off or proportional valves in each link}
11/02	• Systems essentially incorporating special features for controlling the speed or actuating force of an output member
11/022	• • {in which a rapid approach stroke is followed by a slower, high-force working stroke (F15B 11/0325 takes precedence)}
11/024	• by means of differential connection of the servomotor lines, e.g. regenerative circuits
2011/0243	• • • {the regenerative circuit being activated or deactivated automatically}
2011/0246	• • • {with variable regeneration flow}
11/028	• for controlling the actuating force (F15B 11/024 takes precedence)
11/032	by means of fluid-pressure converters
11/0325	• • • { the fluid-pressure converter increasing the working force after an approach stroke }

11/036	• • • by means of servomotors having a plurality of working chambers
11/0365	• • • {Tandem constructions}
11/0303	 for controlling the speed (<u>F15B 11/024</u> takes
11/04	precedence)
11/0406	• • {during starting or stopping (<u>F15B 11/048</u>
	takes precedence)}
11/0413	• • { in one direction only, with no control in the reverse direction, e.g. check valve in parallel with a throttle valve}
11/042	 by means in the feed line {, i.e. "meter in"}(<u>F15B 11/046</u>, <u>F15B 11/05</u> take precedence)
11/0423	• • • {by controlling pump output or bypass, other than to maintain constant speed}
11/0426	• • • {by controlling the number of pumps or parallel valves switched on}
11/044	• • • by means in the return line {, i.e. "meter
	out"}(<u>F15B 11/046</u> , <u>F15B 11/05</u> take precedence)
11/0445	• • • { with counterbalance valves, e.g. to prevent
11/0440	overrunning or for braking}
11/046	• • • depending on the position of the working
	member
11/048	• • • • with deceleration control
11/05	specially adapted to maintain constant speed,
	e.g. pressure-compensated, load-responsive {(<u>F15B 11/161</u> takes precedence)}
11/055	• • • {by adjusting the pump output or bypass}
11/055	 involving features specific to the use of a
	compressible medium, e.g. air, steam
11/064	• with devices for saving the compressible medium
11/068	with valves for gradually putting pneumatic systems under pressure
11/072	Combined pneumatic-hydraulic systems (F15B 11/032 takes precedence)
11/0725	• • • { with the driving energy being derived from
	a pneumatic system, a subsequent hydraulic system displacing or controlling the output element}
11/076	• • • with pneumatic drive or displacement and speed control or stopping by hydraulic braking
11/08	• with only one servomotor
11/10	• • in which the servomotor position is a function of
	the pressure {also pressure regulators as operating means for such systems, the device itself may be a position indicating system}
11/12	• • providing distinct intermediate positions; with
	step-by-step action
11/121	• • • {providing distinct intermediate positions (<u>F15B 11/13</u> takes precedence)}
11/122	• • • {by means of actuators with multiple stops}
11/123	• • • • {by means of actuators with fluid-operated
	stops}
11/125	• • • {by means of digital actuators, i.e. actuators in which the total stroke is the sum of individual strokes}
11/126	• • • {by means of actuators of the standard type with special circuit controlling means
11/127	<pre>(F15B 11/125 takes precedence)} {with step-by-step action}</pre>
11/12/	 {whill step-by-step action} {by means of actuators of the standard type
11/120	with special circuit controlling means}

11/13	• • • using {separate dosing} chambers of
	predetermined volume
11/15	• • with special provision for automatic return
11/16	• with two or more servomotors
11/161	• { with sensing of servomotor demand or load }
11/162	• • • { for giving priority to particular servomotors or users }
11/163	• • { for sharing the pump output equally amongst users or groups of users, e.g. using anti-
	saturation, pressure compensation}
11/165	• • { for adjusting the pump output or bypass in response to demand }
11/166	• • • {Controlling a pilot pressure in response to the load, i.e. supply to at least one user is regulated by adjusting either the system pilot pressure or one or more of the individual pilot command pressures}
11/167	• • • {using pilot pressure to sense the demand}
11/168	• • { with an isolator valve (duplicating valve), i.e. at least one load sense [LS] pressure is derived from a work port load sense pressure but is not a work port pressure itself}
11/17	• • using two or more pumps
11/18	• used in combination for obtaining stepwise operation of a single controlled member
11/183	• • {Linear stepwise operation}
11/186	• • {Rotary stepwise operation}
11/20	• controlling several interacting or sequentially- operating members
11/205	• • • { the position of the actuator controlling the fluid flow to the subsequent actuator }
11/22	• Synchronisation of the movement of two or more
	servomotors
13/00	servomotors
13/00	-
13/00	servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves
	servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems}
13/00 2013/002	servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} . {Modular valves, i.e. consisting of an assembly of
2013/002	servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} . {Modular valves, i.e. consisting of an assembly of interchangeable components}
2013/002 2013/004	servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} . {Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves}
2013/002	servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} . {Modular valves, i.e. consisting of an assembly of interchangeable components}
2013/002 2013/004	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable
2013/002 2013/004 2013/006	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components}) {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds}
2013/002 2013/004 2013/006 2013/008	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding}
2013/002 2013/004 2013/006 2013/008 13/01	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices
2013/002 2013/004 2013/006 2013/008 13/01 13/015	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components}) {Cartridge valves} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} {Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Flow-dividers; Priority valves} {Excess flow valves, e.g. for locking cylinders in
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Flow-dividers; Priority valves}
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022 13/023	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Excess flow valves, e.g. for locking cylinders in case of hose burst}
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022 13/023 13/024	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Excess flow valves, e.g. for locking cylinders in case of hose burst} {Pressure relief valves}
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022 13/023 13/024 13/025	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Excess flow valves, e.g. for locking cylinders in case of hose burst} {Pressure relief valves} {Pressure reducing valves}
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022 13/023 13/023 13/024 13/025 13/026	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Excess flow valves, e.g. for locking cylinders in case of hose burst} {Pressure reducing valves} {Pressure reducing valves} {Pressure compensating valves}
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022 13/023 13/024 13/025 13/026 13/027 13/028 13/029	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Excess flow valves, e.g. for locking cylinders in case of hose burst} {Pressure relief valves} {Pressure compensating valves} {Check valves} {Check valves} {Chuttle valves} {Chuttle valves} {Counterbalance valves}
2013/002 2013/004 2013/006 2013/008 13/01 13/015 13/02 13/021 13/022 13/023 13/024 13/025 13/026 13/027 13/028	 servomotors Details of servomotor systems ({F15B 1/04, F15B 1/26, F15B 3/00, F15B 7/08, F15B 11/02, F15B 11/10,} F15B 15/00 take precedence){; Valves for servomotor systems} (Modular valves, i.e. consisting of an assembly of interchangeable components} {Cartridge valves} {Modular components with multiple uses, e.g. kits for either normally-open or normally-closed valves, interchangeable or reprogrammable manifolds} {Throttling member profiles} Locking-valves or other detent {i.e. load-holding} devices {using an enclosed pilot flow valve} Fluid distribution or supply devices characterised by their adaptation to the control of servomotors {Valves for interconnecting the fluid chambers of an actuator} {Excess flow valves, e.g. for locking cylinders in case of hose burst} {Pressure reducing valves} {Pressure compensating valves} {Check valves} {Check valves} {Shuttle valves}

13/0401	• • • {Valve members; Fluid interconnections
	therefor }
13/0402	• • • {for linearly sliding valves, e.g. spool
13/0403	valves} {a secondary valve member sliding within
13/0403	the main spool, e.g. for regeneration flow
	(F15B 13/0418 takes precedence)}
13/0405	• • • • {for seat valves, i.e. poppet valves}
13/0406	• • • {for rotary valves}
13/0407	• • • • {Means for damping the valve member
	movement}
2013/0409	• • • • {Position sensing or feedback of the valve
	member}
2013/041	•••• {with two positions}
2013/0412	• • • {with three positions}
2013/0413	{with four or more positions}
2013/0414 13/0416	 {Dosing devices} {with means or adapted for load sensing}
13/0410	• • • {Load sensing elements; Internal fluid
13/0417	connections therefor; Anti-saturation or
	pressure-compensation valves}
13/0418	• • • • {Load sensing elements sliding within a
	hollow main valve spool}
13/042	• • • operated by fluid pressure {(<u>F15B 13/0401</u> ,
	<u>F15B 13/0416</u> take precedence)}
13/0422	• • • {with manually-operated pilot valves, e.g.
12/0424	joysticks}
13/0424	• • • • {the joysticks being provided with electrical switches or sensors}
13/0426	• • • • {with fluid-operated pilot valves, i.e.
15/0120	multiple stage valves}
2013/0428	•••• {with switchable internal or external pilot
	pressure source}
13/043	with electrically-controlled pilot valves
13/0431	• • • • {the electrical control resulting in an on-
12/2422	off function}
13/0433	{the pilot valves being pressure control valves (F15B 13/0435, F15B 13/0436,
	F15B $13/0438$ take precedence)
13/0435	• • • • {the pilot valves being sliding valves}
13/0436	• • • • {the pilot valves being of the steerable jet
	type}
13/0438	• • • • {the pilot valves being of the nozzle-
	flapper type}
13/044	• • • operated by electrically-controlled means, e.g.
13/0442	solenoids, torque-motors { with proportional solenoid allowing stable
13/0442	• • • • {with proportional solenoid allowing stable intermediate positions}
13/0444	• • • • {with rotary electric motor}
13/0446	• • • • {with moving coil, e.g. voice coil}
2013/0448	• • • • {Actuation by solenoid and permanent
	magnet }
13/06	for use with two or more servomotors
13/07	• • • in distinct sequence
13/08	Assemblies of units, each for the control of a
12/0002	single servomotor only
13/0803	{Modular units}
13/0807	 {Manifolds} {Laminated constructions}
13/081 13/0814	{Laminated constructions}
13/0814	{Multiblock manifolds}
13/0821	• • • • • {Attachment or sealing of modular units to
15/0021	each other}
	- ,

13/0825	••••• {the modular elements being mounted on a common member, e.g. on a rail}
13/0828	• • • • {characterised by sealing means of the modular units}
13/0832	• • • • • {Modular valves}
13/0835	• • • • • {Cartridge type valves}
13/0839	••••• {Stacked plate type valves}
13/0842	• • • • • • {Monoblock type valves, e.g. with
	multiple valve spools in a common
	housing}
13/0846	• • • • • {Electrical details}
13/085	• • • • • • {Electrical controllers}
13/0853	••••• {Electric circuit boards}
13/0857	••••• {Electrical connecting means, e.g. plugs, sockets}
13/086	••••• {Sensing means, e.g. pressure sensors}
13/0864	••••• {Signalling means, e.g. LEDs}
13/0867	••••• {Data bus systems}
13/0871	•••• {Channels for fluid}
13/0875	{Channels for electrical components, e.g.
	for cables or sensors}
13/0878	{Assembly of modular units}
13/0882	••••• {using identical modular elements}
13/0885	• • • • • {using valves combined with other
12/0000	components}
13/0889	{Valves combined with electrical components}
13/0892	• • • • • • {Valves combined with fluid
	components}
13/0896	{using different types or sizes of valves}
13/10	. Special arrangements for operating the actuated
	device {with or} without using fluid pressure, e.g.
10/10	for emergency use
13/12	• Special measures for increasing the sensitivity of the system
13/14	• Special measures for giving the operating person a
	"feeling" of the response of the actuated device
13/16	• Special measures for feedback {, e.g. by a follow-up
	device}
15/00	Fluid-actuated devices for displacing a member
	from one position to another; Gearing associated
15/02	therewith
15/02	• Mechanical layout characterised by the means for
	converting the movement of the fluid-actuated element into movement of the finally-operated
	member
15/04	• • with oscillating cylinder
15/06	• for mechanically converting rectilinear movement
	into non- rectilinear movement
15/061	• • • {by unidirectional means}
15/063	• • • {Actuator having both linear and rotary output,
	i.e. dual action actuator}
15/065	• • • {the motor being of the rack-and-pinion type}
15/066	• • • {the motor being of the scotch yoke type}
15/068	• • • {the motor being of the helical type}
15/08	• Characterised by the construction of the motor unit
15/082	• {the motor being of the slotted cylinder type}
15/084	• {the motor being of the rodless piston type, e.g. with cable, belt or chain}
15/086	• • • {with magnetic coupling}
15/088	• {the motor using combined actuation, e.g. electric
15/10	and fluid actuation}
15/10	• • the motor being of diaphragm type

15/103	••• {using inflatable bodies that contract when fluid pressure is applied, e.g. pneumatic artificial muscles or McKibben-type actuators}
15/106	• • {the motor being of the pinching-roller type}
15/12	• • of the oscillating-vane or curved-cylinder type
15/125	• • • {of the curved-cylinder type}
15/14	• • of the straight-cylinder type
15/1404	• • • {in clusters, e.g. multiple cylinders in one block}
15/1409	• • • { with two or more independently movable working pistons }
15/1414	• • • {with non-rotatable piston}
15/1419	• • • • {of non-circular cross-section}
15/1423	{Component parts; Constructional details}
15/1428	<pre> {Cylinders (<u>F15B 15/1438</u> takes precedence)}</pre>
15/1433	{End caps (<u>F15B 15/1438</u> takes precedence)}
15/1438	• • • • {Cylinder to end cap assemblies}
15/1442	•••• {End cap sealings}
15/1447	• • • • {Pistons; Piston to piston rod assemblies}
15/1452	{Piston sealings}
15/1457	{Piston rods (<u>F15B 15/1447</u> takes precedence)}
15/1461	• • • • • {Piston rod sealings}
15/1466	• • • {Hollow piston sliding over a stationary rod inside the cylinder}
15/1471	• • • {Guiding means other than in the end cap (<u>F15B 15/1466</u> takes precedence)}
15/1476	{Special return means}
15/148	• • • {Lost-motion means between the piston and the output}
15/1485	• • • {Special measures for cooling or heating}
15/149	• • {Fluid interconnections, e.g. fluid connectors, passages}
2015/1495	• • {with screw mechanism attached to the piston}
15/16	• • • of the telescopic type
15/165	• • • { with synchronisation of sections }
15/17	• • • of differential-piston type
15/18	• Combined units comprising both motor and pump
15/19	• Pyrotechnical actuators
15/20	• Other details {, e.g. assembly with regulating devices}
15/202	• • {Externally-operated valves mounted in or on the actuator}
15/204	 {Control means for piston speed or actuating force without external control, e.g. control valve inside the piston (<u>F15B 11/02</u>, <u>F15B 15/22</u> take precedence)}
2015/206	• • {Combined actuation, e.g. electric and fluid actuated}
2015/208	• • {Special fluid pressurisation means, e.g. thermal or electrolytic}
15/22	• for accelerating or decelerating the stroke
15/221	• • { for accelerating the stroke, e.g. by area increase }
15/222	 . • {having a piston with a piston extension or piston recess which throttles the main fluid outlet as the piston approaches its end position}
15/223	• • {having a piston with a piston extension or piston recess which completely seals the main fluid outlet as the piston approaches its end position}

15/224	••• {having a piston which closes off fluid outlets in the cylinder bore by its own movement}
15/225	• • { with valve stems operated by contact with the piston end face or with the cylinder wall}
15/226	 . • {having elastic elements, e.g. springs, rubber pads}
15/227	• • {having an auxiliary cushioning piston within the main piston or the cylinder end face}
15/228	• • • {having shock absorbers mounted outside the actuator housing}
15/24	• • for restricting the stroke
15/26	Locking mechanisms
15/261	• • • {using positive interengagement, e.g. balls and grooves, for locking in the end positions}
15/262	• • • {using friction, e.g. brake pads}
15/264	• • • {Screw mechanisms attached to the piston}
15/265	• • • {specially adapted for rodless pistons or slotted cylinders}
2015/267	• • • {Manual locking or release}
2015/268	• • • {Fluid supply for locking or release
	independent of actuator pressurisation}
15/28	• • Means for indicating the position, e.g. end of stroke
15/2807	 . {Position switches, i.e. means for sensing of discrete positions only, e.g. limit switches}
15/2815	• • • {Position sensing, i.e. means for continuous measurement of position, e.g. LVDT}
15/2823	• • • • {by a screw mechanism attached to the piston}
15/283	• • • {using a cable wrapped on a drum and attached to the piston}
15/2838	• • • {with out using position sensors, e.g. by volume flow measurement or pump speed}
15/2846	• • • {using detection of markings, e.g. markings on the piston rod}
15/2853	• • • {using potentiometers}
15/2861	• • • • {using magnetic means}
15/2869	• • • { using electromagnetic radiation, e.g. radar or microwaves }
15/2876	•••• {using optical means, e.g. laser}
15/2884	• • • • {using sound, e.g. ultrasound}
15/2892	• • {characterised by the attachment means}
17/00	Combinations of telemotor and servomotor systems
17/02	• in which a telemotor operates the control member of a servomotor
10/00	
18/00	Parallel arrangements of independent servomotor systems
19/00	Testing; {Calibrating; Fault detection or monitoring; Simulation or modelling of} fluid- pressure systems or apparatus not otherwise provided for
19/002	• {Calibrating}
19/005	• {Fault detection or monitoring}
19/007	• {Simulation or modelling}
20/00	Safety arrangements for fluid actuator systems; Applications of safety devices in fluid actuator systems; Emergency measures for fluid actuator systems
20/001	• {Double valve requiring the use of both hands simultaneously}

20/002	• {Electrical failure}
20/004	• {Fluid pressure supply failure}
20/005	• {Leakage; Spillage; Hose burst}
20/007	• {Overload}
20/008	• {Valve failure}
21/00	Common features of fluid actuator systems; Fluid-
	pressure actuator systems or details thereof, not covered by any other group of this subclass
21/001	• {Servomotor systems with fluidic control}
21/001	 {Setvolutor systems with fundic control} {Systems with different interchangeable
21/003	components, e.g. using preassembled kits}
21/005	• {Filling or draining of fluid systems}
21/005	• {Compensation or avoidance of ambient pressure
	variation}
21/008	• {Reduction of noise or vibration}
21/02	• Servomotor systems with programme control
	derived from a store or timing device; Control devices therefor
21/04	• Special measures taken in connection with the properties of the fluid
21/041	• Removal or measurement of solid or liquid
	contamination, e.g. filtering
21/042	Controlling the temperature of the fluid
21/0423	Cooling
21/0427	• • • Heating
21/044	• Removal or measurement of undissolved gas, e.g. de-aeration, venting or bleeding
21/045	Compensating for variations in viscosity or
21/045	temperature
21/047	• Preventing foaming, churning or cavitation
21/048	• • Arrangements for compressed air preparation,
	e.g. comprising air driers, air condensers, filters, lubricators or pressure regulators
21/06	• Use of special fluids, e.g. liquid metal; Special
	adaptations of fluid-pressure systems, or control of elements therefor, to the use of such fluids
21/065	• {Use of electro- or magnetosensitive fluids, e.g.
	electrorheological fluid}
21/08	. Servomotor systems incorporating electrically
	operated control means (<u>F15B 21/02</u> ,
	$\{F15B \ 21/065\}$ take precedence)
21/082	• {with different modes}
21/085	• {using a data bus, e.g. "CANBUS"}
21/087	• {Control strategy, e.g. with block diagram}
21/10 21/12	Delay devices or arrangementsFluid oscillators or pulse generators
21/12	 Fund oscillators or pulse generators {by means of a rotating valve}
21/125	Energy-recuperation means
2201/00	Accumulators
2201/20 2201/205	Accumulator cushioning means using gas
2201/203	using gas using springs
2201/21	using weights
2201/213	using weights using elastic housings
2201/22	Accumulator separating means
2201/305	without separating means
2201/31	• • having rigid separating means, e.g. pistons
2201/312	••• Sealings therefor, e.g. piston rings
2201/315	• • having flexible separating means
2201/3151	the flexible separating means being diaphragms
	or membranes
2201/3152	• • • the flexible separating means being bladders

2201/3153	• • • the flexible separating means being bellows
2201/3154	• • • the flexible separating means being completely enclosed, e.g. using gas-filled balls or foam
2201/3155	• • • characterised by the material of the flexible
2201/3133	separating means
2201/3156	• • • characterised by their attachment
2201/3157	• • • Sealings for the flexible separating means
2201/3158	• • • Guides for the flexible separating means, e.g.
2201/3130	for a collapsed bladder
2201/32	having multiple separating means, e.g. with an
	auxiliary piston sliding within a main piston, multiple membranes or combinations thereof
2201/40	• Constructional details of accumulators not otherwise
	provided for
2201/405	• • Housings
2201/4053	• • • characterised by the material
2201/4056	• • • characterised by the attachment of housing
	components
2201/41	• • Liquid ports
2201/411	• • • having valve means
2201/413	• • • having multiple liquid ports
2201/415	Gas ports
2201/4155	• • • having valve means
2201/42	Heat recuperators for isothermal compression and
000111-	expansion
2201/43	• Anti-extrusion means
2201/435	• • • being fixed to the separating means
2201/50	 Monitoring, detection and testing means for accumulators
2201/505	• Testing of accumulators, e.g. for testing tightness
2201/50	Pressure detection
2201/51	Position detection for separating means
2201/515	 Assembling or methods for making accumulators
2201/605	Assembling or methods for making housings
2201/005	therefor
2201/61	• • Assembling or methods for making separating
	means therefor
2201/615	. Assembling or methods for making ports therefor
2211/00	Circuits for servomotor systems
2211/20	• Fluid pressure source, e.g. accumulator or variable
	axial piston pump
2211/205	• • Systems with pumps
2211/20507	
2211/20515	
2211/20523	8
2211/2053	Type of pump
2211/20538	1 5
2211/20546	· · · · · · · · · · · · · · · · · · ·
2211/20553	•••• with pilot circuit, e.g. for controlling a swash plate
2211/20561	-
2211/20569	
2211/20509	
2211/20570	
2211/20304	capacity
2211/20592	
	and low pressure
2211/21	• • Systems with pressure sources other than pumps,
	e.g. with a pyrotechnical charge
2211/212	• • • the pressure sources being accumulators
2211/214	• • • the pressure sources being hydrotransformers

2211/216	• • • the pressure sources being pneumatic-to-
2211/210	hydraulic converters
2211/218	• • • the pressure sources being pyrotechnical charges
2211/25	Pressure control functions
2211/251	• • High pressure control
2211/251	Low pressure control
2211/252	-
2211/233	• • Pressure margin control, e.g. pump pressure in relation to load pressure
2211/255	Flow control functions
2211/26	• • Power control functions
2211/265	• Control of multiple pressure sources
2211/2652	without priority
2211/2654	• • • one or more pressure sources having priority
2211/2656	 by control of the pumps
2211/2658	 by control of the prime movers
2211/27	. Directional control by means of the pressure source
2211/275	• • Control of the prime mover, e.g. hydraulic control
2211/30	Directional control
2211/305	• characterised by the type of valves
2211/30505	• • Non-return valves, i.e. check valves
2211/3051	Cross-check valves
2211/30515	Load holding valves
2211/3052	••••••••••••••••••••••••••••••••••••••
	Directional control valves, e.g. 4/3-directional
2211/30323	control valve
2211/3053	In combination with a pressure compensating
	valve
2211/30535	• • • • • the pressure compensating valve is
	arranged between pressure source and
	directional control valve
2211/3054	• • • • • the pressure compensating valve is
	arranged between directional control valve
	and output member
2211/30545	• • • • the pressure compensating valve is
	arranged between output member and
	directional control valve
2211/3055	• • • • the pressure compensating valve is
	arranged between directional control valve
	and return line
2211/30555	
	compensating valve being connected to the
	directional control valve
2211/3056	Assemblies of multiple valves
2211/30565	• • • having multiple valves for a single output
	member, e.g. for creating higher valve
	function by use of multiple valves like two
	2/2-valves replacing a 5/3-valve
2211/3057	having two valves, one for each port of a
	double-acting output member
2211/30575	in a Wheatstone Bridge arrangement (also
	half bridges)
2211/3058	having additional valves for
	interconnecting the fluid chambers
	of a double-acting actuator, e.g. for regeneration mode or for floating mode
	(directional control valves having a regenerative position <u>F15B 2211/3133;</u>
	directional control valves having a floating
	position <u>F15B 2211/3127</u>)
2211/30585	• • • having a single valve for multiple output
2211/30303	members

2211/3059	• • • having multiple valves for multiple output members
2211/30595	• • • • with additional valves between the groups of valves for multiple output members
2211/31	• characterised by the positions of the valve element
2211/3105	Neutral or centre positions
2211/3111	• • • • the pump port being closed in the centre
2211/3111	position, e.g. so-called closed centre
2211/2116	
2211/3116	• • • the pump port being open in the centre
0011/0100	position, e.g. so-called open centre
2211/3122	• • • Special positions other than the pump port
	being connected to working ports or the
	working ports being connected to the return
	line
2211/3127	Floating position connecting the working
	ports and the return line
2211/3133	Regenerative position connecting the
	working ports or connecting the working
	ports to the pump, e.g. for high-speed
	approach stroke
2211/3138	the positions being discrete
2211/3144	• • • the positions being continuously variable, e.g.
	as realised by proportional valves
2211/315	• characterised by the connections of the valve or
	valves in the circuit
2211/31505	
2211/51505	return line
2211/31511	• • • having a single pressure source
2211/31517	having a single pressure source
2211/31523	• • • being connected to a pressure source and an
2211/21520	output member
2211/31529	
	output member
2211/31535	having multiple pressure sources and a single
	output member
2211/31541	0 0 1 I I I I I I I I I I I I I I I I I
2211/21545	output members
2211/31547	having multiple pressure sources and
	multiple output members
2211/31552	
	return line
2211/31558	having a single output member
2211/31564	
2211/3157	• • • being connected to a pressure source, an output
	member and a return line
2211/31576	
	output member
2211/31582	
	output member
2211/31588	
	output members
2211/31594	
	multiple output members
2211/32	• • characterised by the type of actuation
2211/321	mechanically
2211/322	• • • • actuated by biasing means, e.g. spring-
	actuated
2211/323	•••• the biasing means being adjustable
2211/324	• • • manually, e.g. by using a lever or pedal
2211/325	••••••••••••••••••••••••••••••••••••••
2211/326	••••••••••••••••••••••••••••••••••••••
2211/320	• • • • • • • • • • • • • • • • • • •
22111321	•••• electroary of electromeany

2211/326	•	•	•	• • wit
2211/327		•	•	electrica
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2211/328	• • • with signal modulation, e.g. pulse width modulation [PWM]
2211/329	• • • actuated by fluid pressure
2211/35	. Directional control combined with flow control
2211/351	Flow control by regulating means in feed line,
	i.e. meter-in control
2211/353	• • Flow control by regulating means in return line,
2211/333	i.e. meter-out control
0011/055	
2211/355	• Pilot pressure control
2211/36	• Pilot pressure sensing
2211/365	Directional control combined with flow control
	and pressure control
2211/40	• Flow control
2211/405	• characterised by the type of flow control means or
2211/100	valve
2211/40507	• • • with constant throttles or orifices
	with variable throttles or orifices
2211/40523	
2211/4053	8
2211/40538	• • • using volumetric pumps or motors
2211/40546	
2211/40553	• • • with pressure compensating valves
2211/40561	the pressure compensating valves arranged
2211/40301	upstream of the flow control means
2211/405/0	
2211/40509	• • • • the pressure compensating valve arranged
	downstream of the flow control means
2211/40576	1
2211/40584	
	with a check valve
2211/40592	• • • with multiple valves in parallel flow paths,
2211/41	• characterised by the positions of the valve
	element
2211/411	• • • the positions being discrete
2211/413	• • • the positions being continuously variable, e.g.
2211/415	as realised by proportional valves
2211/415	 characterised by the connections of the flow
2211/415	control means in the circuit
2211/41500	
2211/41509	
	directional control valve
2211/41518	8 1 1
2211/41527	
	directional control valve
2211/41536	• • • being connected to multiple ports of an
	output member
2211/41545	• • • being connected to multiple output members
2211/41554	• • • being connected to a return line and a
	directional control valve
2211/41563	
2211/71303	return line
2211/41572	
2211/41572	E I
0011/41201	output member
2211/41581	
	return line
2211/4159	• • • being connected to a pressure source, an output
	member and a return line
2211/42	• • characterised by the type of actuation
2211/421	mechanically
2211/422	• • • actuated by biasing means, e.g. spring-
	actuated
2211/423	• • • manually, e.g. by using a lever or pedal
2211/423	 actuated by an output member of the circuit
	••••• with follow-up action
2211/425	· · · · · · · · · · · · · · · · · · ·
0011/10-	
2211/426	• • • electrically or electronically

2211/427	•••• with signal modulation, e.g. using pulse width modulation [PWM]
2211/428	• • • actuated by fluid pressure
2211/45	• Control of bleed-off flow, e.g. control of bypass flow to the return line
2211/455	• Control of flow in the feed line, i.e. meter-in control
2211/46	• Control of flow in the return line, i.e. meter-out control
2211/465	. Flow control with pressure compensation
2211/47	• Flow control in one direction only
2211/473	• • • without restriction in the reverse direction
2211/476	• • • the flow in the reverse direction being blocked
2211/1/0	 Pressure control
2211/505	
	• characterised by the type of pressure control means
2211/50509	pressure upstream of the pressure control means
2211/50518	using pressure relief valves
2211/50527	• • • • using cross-pressure relief valves
2211/50536	• • • using unloading valves controlling the supply pressure by diverting fluid to the return line
2211/50545	• • • using braking valves to maintain a back pressure
2211/50554	1 0
	pressure downstream of the pressure control
	means, e.g. pressure reducing valve
2211/50563	the pressure control means controlling a differential pressure
2211/50572	using a pressure compensating valve for controlling the pressure difference across a flow control valve
2211/50581	• • • using counterbalance valves
2211/5059	• • • • • using double counterbalance valves
2211/51	• characterised by the positions of the valve element
2211/511	• • • the positions being discrete
2211/513	• • • the positions being continuously variable, e.g.
2211/515	 as realised by proportional valves characterised by the connections of the pressure
2211/515	 control means in the circuit being connected to a pressure source and a
2211/5151	directional control valve
2211/5152	being connected to multiple pressure sources
2211/5153	• • • • • • • • • • • • • • • • • • •
2211/5155	 directional control valve being connected to an output member and a directional control valve
2211/3134	output member
2211/5155	• • • being connected to multiple output members
2211/5156	• • • being connected to a return line and a
2211/0100	directional control valve
2211/5157	• • • being connected to a pressure source and a return line
2211/5158	• • being connected to a pressure source and an output member
2211/5159	• • • being connected to an output member and a return line
2211/52	• characterised by the type of actuation
2211/521	mechanically
2211/522	• • • • actuated by biasing means, e.g. spring-
	actuated
2211/523	• • • manually, e.g. by using a lever or pedal

2211/524	• • • • actuated by an output member of the circuit
2211/525	• • • • with follow-up action
2211/526	• • • electrically or electronically
2211/527	•••• with signal modulation, e.g. pulse width modulation [PWM]
2211/528	actuated by fluid pressure
2211/55	. for limiting a pressure up to a maximum pressure,
	e.g. by using a pressure relief valve
2211/555	• for assuring a minimum pressure, e.g. by using a
	back pressure valve
2211/56	Control of an upstream pressure
2211/565	. Control of a downstream pressure
2211/57	Control of a differential pressure
2211/575	. Pilot pressure control
2211/5753	• • • for closing a valve
2211/5756	for opening a valve
2211/60	• Circuit components or control therefor
2211/605	• • Load sensing circuits
2211/6051	• • • having valve means between output member
	and the load sensing circuit
2211/6052	• • • • using check valves
2211/6054	• • • • using shuttle valves
2211/6055	•••• using pressure relief valves
2211/6057	• • • • using directional control valves
2211/6058	• • • with isolator valves
2211/61	• • Secondary circuits
2211/611	Diverting circuits, e.g. for cooling or filtering
2211/613	Feeding circuits
2211/615	• • Filtering means
2211/62	. Cooling or heating means
2211/625	. Accumulators
2211/63	. Electronic controllers
2211/6303	• • using input signals
2211/6306	•••• representing a pressure
2211/6309	••••••••••••••••••••••••••••••••••••••
	supply pressure
2211/6313	• • • • • the pressure being a load pressure
2211/6316	• • • • • the pressure being a pilot pressure
2211/632	representing a flow rate
2211/6323	the flow rate being a pressure source flow
	rate
2211/6326	• • • • • the flow rate being an output member flow
	rate
2211/633	• • • representing a state of the prime mover, e.g.
	torque or rotational speed
2211/6333	• • • representing a state of the pressure source,
00///	e.g. swash plate angle
2211/6336	representing a state of the output member,
0011/004	e.g. position, speed or acceleration
2211/634	• • • • representing a state of a valve
2211/6343	representing a temperature
2211/6346	• • • representing a state of input means, e.g.
2211/625	joystick position
2211/635	Circuits providing pilot pressure to pilot pressure- controlled fluid circuit elements
2211/6255	having valve means
2211/6355 2211/65	
2211/65	 Methods of control of the foad sensing pressure characterised by the way the load pressure is
2211/031	communicated to the load sensing circuit
2211/652	• • • the load sensing pressure being different from
2211/032	the load pressure
2211/653	• • • the load sensing pressure being higher than the
	load pressure

2211/654	• • • the load sensing pressure being lower than the
	load pressure
2211/655	• • Methods of contamination control, i.e. methods of
	control of the cleanliness of circuit components or
2211/66	of the pressure fluid
2211/66	. Temperature control methods
2211/665	• Methods of control using electronic components
2211/6651	Control of the prime mover, e.g. control of the
2211/6652	output torque or rotational speed ••• Control of the pressure source, e.g. control of
2211/0032	the swash plate angle
2211/6653	Pressure control
2211/6654	Flow rate control
2211/6655	 Power control, e.g. combined pressure and flow
2211/0000	rate control
2211/6656	Closed loop control, i.e. control using feedback
2211/6657	• • • Open loop control, i.e. control without
	feedback
2211/6658	Control using different modes, e.g. four-
	quadrant-operation, working mode and
	transportation mode
2211/67	• • Methods for controlling pilot pressure
2211/70	• Output members, e.g. hydraulic motors or cylinders
0011/77	or control therefor
2211/705	• characterised by the type of output members or
0011/7071	actuators
2211/7051	Linear output members
2211/7052	Single-acting output members
2211/7053	Double-acting output members
2211/7054 2211/7055	• • • • Having equal piston areas
	having more than two chambers
2211/7056 2211/7057	••••• Tandem cylinders
2211/7057	being of the telescopic type
2211/7038	Rotary output membersMultiple output members, e.g. multiple hydraulic
2211/71	motors or cylinders
2211/7107	• • • the output members being mechanically linked
2211/7114	••••••••••••••••••••••••••••••••••••••
	different actuators
2211/7121	• • • • the chambers being connected in series
2211/7128	• • • • the chambers being connected in parallel
2211/7135	Combinations of output members of different
	types, e.g. single-acting cylinders with rotary
	motors
2211/7142	• • • the output members being arranged in multiple
	groups
2211/715	• • having braking means
2211/72	• having locking means
2211/75	• Control of speed of the output member
2211/755	Control of acceleration or deceleration of the autout member
2211/76	output member Control of force or torque of the output member
2211/76	Control of force or torque of the output member Control of a negative load, i.e. of a load
2211/701	Control of a negative load, i.e. of a load generating hydraulic energy
2211/763	• • Control of torque of the output member by
	means of a variable capacity motor, i.e. by a
	secondary control on the motor
2211/765	• • Control of position or angle of the output member
2211/7653	• • • at distinct positions, e.g. at the end position
2211/7656	• • • with continuous position control
2211/77	• • Control of direction of movement of the output
	member
2211/7708	in one direction only

2211/7716	• • • with automatic return
2211/7725	• • • with automatic reciprocation
2211/7733	• • • providing vibrating movement, e.g. dither
2211/7741	control for emptying a bucket
2211/7741	• • • with floating mode, e.g. using a direct connection between both lines of a double-
	acting cylinder
2211/775	Combined control, e.g. control of speed and force
2211/1/5	for providing a high speed approach stroke with
	low force followed by a low speed working stroke
	with high force, e.g. for a hydraulic press
2211/78	• • Control of multiple output members
2211/781	one or more output members having priority
2211/782	Concurrent control, e.g. synchronisation of two
	or more actuators
2211/783	Sequential control
2211/785	• Compensation of the difference in flow rate in
	closed fluid circuits using differential actuators
2211/80	• Other types of control related to particular problems
2211/05	or conditions
2211/85	Control during special operating conditions
2211/851 2211/853	during starting during stopping
2211/855	. during stopping. Testing of fluid pressure systems
2211/855	Monitoring of fluid pressure systems
2211/857	Control during or prevention of abnormal
2211/00	conditions
2211/8603	• • • the abnormal condition being an obstacle
2211/8606	• • • the abnormal condition being a shock
2211/8609	the abnormal condition being cavitation
2211/8613	• • • the abnormal condition being oscillations
2211/8616	• • • the abnormal condition being noise or vibration
2211/862	• • • the abnormal condition being electric or
	electronic failure
2211/8623	• • • Electric supply failure
2211/8626	Electronic controller failure, e.g. software,
2211/972	EMV, electromagnetic interference
2211/863	• • • the abnormal condition being a hydraulic or pneumatic failure
2211/8633	Pressure source supply failure
2211/8636	Circuit failure, e.g. valve or hose failure
2211/864	•••• Failure of an output member, e.g. actuator or
	motor failure
2211/8643	• • • the abnormal condition being a human failure
2211/8646	• • • the abnormal condition being hysteresis
2211/865	. Prevention of failures
2211/87	. Detection of failures
2211/875	• Control measures for coping with failures
2211/8752	• • Emergency operation mode, e.g. fail-safe operation mode
2211/8755	
2211/8755	 Emergency shut-down using redundant components or assemblies
2211/8737 2211/88	Control measures for saving energy
2211/885	Control specific to the type of fluid, e.g. specific
2211/005	to magnetorheological fluid
2211/8855	• • • Compressible fluids, e.g. specific to pneumatics
2211/89	. Control specific for achieving vacuum or
	"negative pressure"
2211/895	Manual override
2215/00	Fluid-actuated devices for displacing a member
	from one position to another
2215/30	Constructional details thereof

2215/305 . . characterised by the use of special materials