CPC COOPERATIVE PATENT CLASSIFICATION

G PHYSICS

(NOTES omitted)

INSTRUMENTS

G01 MEASURING; TESTING

(NOTES omitted)

G01P MEASURING LINEAR OR ANGULAR SPEED, ACCELERATION, DECELERATION, OR SHOCK; INDICATING PRESENCE, ABSENCE, OR DIRECTION, OF

MOVEMENT (measuring or recording blood flow A61B 5/02, A61B 8/06; monitoring speed or deceleration of electrically-propelled vehicles B60L 3/00; vehicle lighting systems adapted to indicate speed B60Q 1/54; determining position or course in navigation, measuring ground distance in geodesy or surveying G01C; combined measuring devices for measuring two or more variables of movement G01C 23/00; measuring velocity of sound G01H; measuring velocity of light G01J 7/00; measuring direction or velocity of solid objects by reception or emission of radiowaves or other waves and based on propagation effects, e.g. Doppler effect, propagation time, direction of propagation, G01S; measuring speed of nuclear radiation G01T; measuring acceleration of gravity G01V; {measuring or recording the speed of trains B61L 23/00; speed indicators incorporated in motor vehicles B60K 35/00; measuring frequency or phase G01R; traffic control G08G})

NOTES

- 1. This subclass <u>covers</u> measuring direction or velocity of flowing fluids using propagation effects of radiowaves or other waves caused in the fluid itself, e.g. by laser anemometer, by ultrasonic flowmeter with "sing-around-system".
- 2. Attention is drawn to the Notes following the title of class <u>G01</u>.

two impulses with a reference time}

WARNING

In this subclass non-limiting references (in the sense of paragraph 39 of the Guide to the IPC) may still be displayed in the scheme.

1/00	Details of instruments	1/11	by the detection of the position of the
1/003	• {used for damping}		indicator needle
1/006	• {used for thermal compensation}	1/12	• Recording devices (indicating working conditions of
1/02	. Housings		vehicles <u>G07C 5/00</u>)
1/023	• • {for acceleration measuring devices}	1/122	• • {Speed recorders}
1/026	• • {for speed measuring devices, e.g. pulse	1/125	• • { with recording discs }
	generator}	1/127	• • {for acceleration values}
1/04	Special adaptations of driving means	1/14	• • for permanent recording {(G01P 1/125 takes
1/06	• {Indicating or recording devices, e.g. for remote		precedence)}
	indication (indicating or recording in general <u>G01D</u> ;	1/16	for erasable recording, e.g. magnetic recording
1/07	registering or indicating working conditions of vehicles G07C 5/00)} Indicating devices, e.g. for remote indication (indicating working conditions of vehicles G07C 5/00) Arrangements of scales, pointers, lamps or acoustic indicators, e.g. in automobile speedometers	3/00	Measuring linear or angular speed; Measuring differences of linear or angular speeds (G01P 5/00 - G01P 11/00 take precedence; {direction and speed indication G01P 13/045}; counting mechanisms G06M) NOTE The sub-groups of this group are distinguished
1/10 1/103	 for indicating predetermined speeds {by comparing the value of the measured signal with one or several reference values (in general G01R 17/00)} {by comparing the time duration between 		by the method of measurement which is of major importance. Thus the mere application of other methods for giving a final indication does not affect the classification.

3/02	 Devices characterised by the use of mechanical means 	3/4815	• • • • {using a pulse wire sensor, e.g. Wiegand wire}
3/04	by comparing two speeds	3/482	delivered by nuclear radiation detectors
3/06	using a friction gear	3/483	delivered by variable capacitance detectors
3/08	using differential gearing	3/484	delivered by contact-making switches
3/10	• by actuating an indicating element, e.g. pointer,	3/486	delivered by photo-electric detectors
3/10	for a fixed time	3/487	delivered by rotating magnets
3/12	by making use of a system excited by impact	3/488	delivered by variable reluctance detectors
3/14	by making use of a system excited by impact by exciting one or more mechanical resonance		
3/14		3/489	Digital circuits therefor
2/16	systems	3/49	using eddy currents
3/16	• • by using centrifugal forces of solid masses {(governors <u>G05D 13/10</u>)}	3/495	• • • • where the indicating means responds to forces produced by the eddy currents and the
3/18	transferred to the indicator by mechanical means	3/4953	generating magnetic field {with a counter for the covered distance
3/20	transferred to the indicator by fluid means	3/4933	incorporated (measuring the covered
3/20	transferred to the indicator by find means transferred to the indicator by electric or		distance G01C 22/00)}
3/22	magnetic means	2/4056	
2/24	<u>e</u>	3/4956	• • • • {with thermal compensation}
3/24	• by using friction effects (G01P 3/06 takes	3/50	• • for measuring linear speed (G01P 3/56 takes
2/2 -	precedence)		precedence)
3/26	Devices characterised by the use of fluids	3/505	• • · · {by using eddy currents}
3/263	• • {by using fluidic impulse generators}	3/52	• • • by measuring amplitude of generated current or
3/266	• • {by using a vortex chamber}		voltage
3/28	• • by using pumps	3/54	• • • by measuring frequency of generated current or
3/30	by using centrifugal forces of fluids		voltage
3/32	in a rotary container communicating with a	3/56	 for comparing two speeds
	fixed container	3/565	• • • {by measuring or by comparing the phase
3/34	by using friction effects		of generated current or voltage (phase
3/36	. Devices characterised by the use of optical means,		comparators per se H03D 13/00; phase
	e.g. using infrared, visible, or ultraviolet light		measurement <u>G01R 25/00</u>)}
	(G01P 3/68 takes precedence; gyrometers using	3/58	by measuring or comparing amplitudes of
	the Sagnac effect, i.e. rotation-induced shifts		generated currents or voltage {(amplitude
	between counter-rotating electromagnetic beams		comparators H03K 5/24)}
	G01C 19/64)	3/60	by measuring or comparing frequency of
3/363	• • {by using a ring laser (ring lasers in general	2,00	generated currents or voltages {(frequency
3/303	H01S 3/083)}		comparators H03K 5/26)}
3/366	• • {by using diffraction of light (for measuring	3/62	Devices characterised by the determination or
3/300	speed of fluids G01P 5/26)}	3, 62	the variation of atmospheric pressure with height
3/38	• using photographic means		to measure the vertical components of speed
			(measuring pressure in general G01L)
3/40	. using stroboscopic means	3/64	• Devices characterised by the determination of the
3/42	• Devices characterised by the use of electric or	3/04	time taken to traverse a fixed distance
	magnetic means (G01P 3/66 takes precedence;	3/66	• using electric or magnetic means (G01P 3/80)
	measuring electric or magnetic values in general	3/00	
	<u>G01R</u>)		takes precedence; measuring short time intervals G04F 8/00, G04F 10/00)
3/44	• • for measuring angular speed (G01P 3/56 takes	2/665	
	precedence)	3/665	• • • {for projectile velocity measurements}
3/443	• • • {mounted in bearings (bearings <u>F16C</u>)}	3/68	• using optical means, i.e. using infrared, visible, or
3/446	{mounted between two axially spaced rows		ultraviolet light (<u>G01P 3/80</u> takes precedence {;
	of rolling elements}		by reflection of waves $\underline{G01S 17/58}$)
3/46	by measuring amplitude of generated current or	3/685	• • • {for projectile velocity measurements}
	voltage {(in general <u>G01R 19/00</u>)}	3/80	 using auto-correlation or cross-correlation
3/465	{by using dynamo-electro tachometers or		detection means
3/ 103	electric generator}	3/803	• • • {in devices of the type to be classified in
3/48	by measuring frequency of generated current or		<u>G01P 3/66</u> }
3/40	voltage {(in general G01R 23/00)}	3/806	{in devices of the type to be classified in
2/4902		2.200	G01P 3/68}
3/4802	• • • {by using electronic circuits in general}		
3/4805	• • • • {by using circuits for the electrical	5/00	Measuring speed of fluids, e.g. of air stream;
	integration of the generated pulses		Measuring speed of bodies relative to fluids, e.g.
	(measuring impulse frequency by		of ship, of aircraft (application of speed-measuring
	integration <u>G01R 23/09</u>)}		devices for measuring volume of fluid G01F)
3/4807	• • • • {by using circuits for the detection of the	5/001	• {Full-field flow measurement, e.g. determining flow
		3/001	• {Full-field flow measurement, e.g. determining flow
	pulses delivered by the ignition system of	3/001	velocity and direction in a whole region at the same
2, 122,	pulses delivered by the ignition system of an internal combustion engine}	5/001	velocity and direction in a whole region at the same
3/481	pulses delivered by the ignition system of	5/003	

5/005 5/006	 {by using a jet directed into the fluid} • {the jet used is composed of ionised or	13/0006	• {of fluids or of granulous or powder-like substances}
	radioactive particles}	13/0013	• • {by using a solid body which is shifted by the
5/008	• {by using an electrolyte added to the fluid}	12/002	action of the fluid}
5/01 5/02	by using swirlflowmeterby measuring forces exerted by the fluid on solid	13/002	• { with electrical coupling to the indicating devices}
	bodies, e.g. anemometer	13/0026	• • {by using deflection of baffle-plates}
5/04	using deflection of baffle-plates	13/0033	• • { with electrical coupling to the indicating
5/06	• using rotation of vanes (measuring speed of	12/004	device}
5/065	rotating shafts G01P 3/00) • • { with mechanical coupling to the indicating	13/004 13/0046	. {by using the rotation of vanes} {with electrical coupling to the indicating
3/003	device}		device}
5/07	• • • with electrical coupling to the indicating device	13/0053	• • {by using dynamo-electric effect}
5/08	 by measuring variation of an electric variable 	13/006	• • {by using thermal variables}
	directly affected by the flow, e.g. by using dynamo- electric effect	13/0066 13/0073	. {by using differences of pressure in the fluid}. {by using vibrations generated by the fluid}
5/083	• • {by using electronic circuits for measuring the dynamoelectric effect}	13/008	• {by using a window mounted in the fluid carrying tube (G01P 13/0013, G01P 13/0026, G01P 13/004
5/086	• • {by using special arrangements and constructions		take precedence)}
	for measuring the dynamo-electric effect}	13/0086	• • {with photo-electric detection}
5/10	 by measuring thermal variables 	13/0093	• {by making use of products, e.g. chemical products
5/12	using variation of resistance of a heated conductor		added to the fluid in order to make the fluid flow
5/14	. by measuring differences of pressure in the fluid		visible}
5/16	• • using Pitot tubes {, e.g. Machmeter}	13/02	 Indicating direction only, e.g. by weather vane
5/165	Arrangements or constructions of Pitot tubes	13/025	• • {indicating air data, i.e. flight variables of an
5/17	Coupling arrangements to the indicating device		aircraft, e.g. angle of attack, side slip, shear, yaw}
5/175	• • • • with the determination of Mach number (analogue computers therefor G06G 7/57)	13/04	Indicating positive or negative direction of a linear movement or clockwise or anti-clockwise
5/18	 by measuring the time taken to traverse a fixed 		direction of a rotational movement
	distance	13/045	• • • {with speed indication}
5/20	using particles entrained by a fluid stream (G01P 5/22 takes precedence)	15/00	Measuring acceleration; Measuring deceleration;
	(GOTT 5/22 takes precedence)		Measuring shock, i.e. sudden change of
5/22	using auto-correlation or cross-correlation		acceleration
	• using auto-correlation or cross-correlation detection means	15/001	acceleration {by measuring acceleration changes by making use
5/22 5/24	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming 		acceleration{by measuring acceleration changes by making use of a triple differentiation of a displacement signal}
	• using auto-correlation or cross-correlation detection means	15/001 15/003	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring
	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. 		 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference
5/24 5/241	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} 		 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring
5/24	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or 		 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001,
5/24 5/241	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes 	15/003	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)}
5/24 5/241 5/242	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} 	15/003 15/005	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} . {measuring translational acceleration}
5/241 5/241 5/242	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} 	15/003 15/005 15/006	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses}
5/24 5/241 5/242	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves 	15/003 15/005 15/006 15/008 15/02	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence)
5/241 5/241 5/242	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical 	15/003 15/005 15/006 15/008 15/02	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means
5/241 5/241 5/242 5/244 5/245	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} 	15/003 15/005 15/006 15/008 15/02	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable
5/241 5/241 5/242 5/244 5/245	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} 	15/003 15/005 15/006 15/008 15/02 15/03 15/032	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass}
5/241 5/241 5/242 5/244 5/245	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming 	15/003 15/005 15/006 15/008 15/02	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)}
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave 	15/003 15/005 15/006 15/008 15/02 15/03 15/032	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration
5/241 5/242 5/242 5/244 5/245 5/247 5/248	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values}
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means}
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} for indicating maximum value
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of acceleration G01C 21/16) 	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} tor indicating maximum value using members subjected to a permanent
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of acceleration G01C 21/16) Measuring average value of speed (by determining 	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} to rindicating maximum value using members subjected to a permanent deformation
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, 	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06 15/08	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} to the for indicating maximum value using members subjected to a permanent deformation with conversion into electric or magnetic values
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) 	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06 15/08 15/0802	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} to indicating maximum value using members subjected to a permanent deformation with conversion into electric or magnetic values {Details}
5/241 5/242 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, 	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06 15/08 15/0802	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} to rindicating maximum value using members subjected to a permanent deformation with conversion into electric or magnetic values {Details} {being provided with a particular type
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) Measuring average speed of number of bodies, e.g. 	15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06 15/08 15/0802	 acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} {by using members subjected to a permanent deformation with conversion into electric or magnetic values {Details}

2015/0808 {for defining in-plane movement of the mass, i.e. movement of the mass in the plane	2015/088 {for providing wafer-level encapsulation} 2015/0882 {for providing damping of vibrations}
of the substrate}	15/0885 {by magnetostrictive pick-up}
2015/0811 {for one single degree of freedom of	15/0888 { for indicating angular acceleration}
movement of the mass}	15/0891 • • • { with indication of predetermined acceleration
2015/0814 {for translational movement of the mass,	values (<u>G01P 15/135</u> takes precedence)}
e.g. shuttle type}	15/0894 {by non-contact electron transfer, i.e. electron
2015/0817 {for pivoting movement of the mass,	tunneling}
e.g. in-plane pendulum}	15/0897 {by thermal pick-up (<u>G01P 15/008</u> takes
2015/082 {for two degrees of freedom of movement	precedence)}
of a single mass}	15/09 by piezoelectric pick-up
2015/0822 {for defining out-of-plane movement of the	15/0907 {of the compression mode type}
mass}	15/0915 { of the shear mode type}
2015/0825 {for one single degree of freedom of	15/0922 {of the bending or flexing mode type}
movement of the mass}	15/093 by photoelectric pick-up
2015/0828 {the mass being of the paddle type being	15/097 by vibratory elements
suspended at one of its longitudinal	15/0975 {by acoustic surface wave resonators or
ends}	delay lines}
2015/0831 {the mass being of the paddle type	15/10 by vibratory strings
having the pivot axis between the longitudinal ends of the mass, e.g. see-	15/105 by magnetically sensitive devices
saw configuration}	15/11 by inductive pick-up
2015/0834 { the mass constituting a pendulum	15/12 by alteration of electrical resistance
having the pivot axis disposed	{(<u>G01P 15/0897, G01P 15/105</u> take
symmetrically between the longitudinal	precedence)}
ends, the center of mass being shifted	15/121 {by potentiometers}
away from the plane of the pendulum	15/122 {by metal resistance strain gauges, e.g. wire
which includes the pivot axis}	resistance strain gauges}
2015/0837 {the mass being suspended so as to only	15/123 {by piezo-resistive elements, e.g.
allow movement perpendicular to the	semiconductor strain gauges}
plane of the substrate, i.e. z-axis sensor}	15/124 {by semiconductor devices comprising at
2015/084 {the mass being suspended at more than	least one PN junction, e.g. transistors}
one of its sides, e.g. membrane-type	15/125 by capacitive pick-up
suspension, so as to permit multi-axis	15/13 by measuring the force required to restore a
movement of the mass}	proofmass subjected to inertial forces to a null
2015/0842 {the mass being of clover leaf shape}	position
2015/0845 {using a plurality of spring-mass	15/131 { with electrostatic counterbalancing means }
systems being arranged on one common	15/132 { with electromagnetic counterbalancing
planar substrate, the systems not being	means}
mechanically coupled and the sensitive	15/133 { with piezoelectric counterbalancing means}
direction of each system being different}	15/135 by making use of contacts which are actuated
2015/0848 {using a plurality of mechanically coupled	by a movable inertial mass
spring-mass systems, the sensitive direction	15/14 . by making use of gyroscopes (gyroscopes per se
of each system being different}	<u>G01C 19/00</u>)
2015/0851 {using a plurality of spring-mass systems,	15/16 • by evaluating the time-derivative of a measured
each system having a different range of	speed signal
sensitivity to acceleration}	15/165 • • {for measuring angular accelerations}
2015/0854 {using a particular shape of the mass, e.g.	15/18 • in two or more dimensions
annular}	21/00 Testing or calibrating of apparatus or devices
2015/0857 {using a particular shape of the suspension	21/00 Testing or calibrating of apparatus or devices covered by the preceding groups
spring}	21/02 • of speedometers
2015/086 {using a torsional suspension spring}	-
2015/0862 • • • {being provided with particular means being integrated into a MEMS accelerometer	21/025 • • {for measuring speed of fluids; for measuring speed of bodies relative to fluids (for measuring
structure for providing particular additional	volume flow $\underline{G01F 25/10}$)
functionalities to those of a spring mass	Totalic from <u>Golf 25/10</u>))
system}	
2015/0865 {using integrated signal processing circuitry}	
2015/0868 {using self-test structures integrated into the	
microstructure}	
2015/0871 { using stopper structures for limiting the	
travel of the seismic mass}	
2015/0874 {using means for preventing stiction of the	
seismic mass to the substrate}	
2015/0877 {using integrated interconnect structures}	