CPC COOPERATIVE PATENT CLASSIFICATION

G PHYSICS

(NOTES omitted)

INSTRUMENTS

G05 CONTROLLING; REGULATING (NOTES omitted)

G05D SYSTEMS FOR CONTROLLING OR REGULATING NON-ELECTRIC VARIABLES

<u>NOTES</u>

- 1. This subclass <u>does not cover</u> features of general applicability to regulating systems, e.g. anti-hunting arrangements, which are covered by subclass <u>G05B</u>.
- 2. In this subclass, the following term is used with the meaning indicated:
 - "systems" includes self-contained devices such as speed governors, pressure regulators.
- 3. Control systems specially adapted for particular apparatus, machines or processes are classified in the subclasses for the apparatus, machines or processes, provided that there is specific provision for control or regulation relevant to the special adaptation, either at a detailed level, e.g. <u>A21B 1/40</u>: "for regulating temperature in bakers' ovens", or at a general level, e.g. <u>B23K 9/095</u>: "for automatic control of welding parameters in arc welding". Otherwise, classification is made in the most appropriate place in this subclass.

WARNING

In this subclass non-limiting references (in the sense of paragraph 39 of the Guide to the IPC) may still be displayed in the scheme.

1/00 Control of position, course, altitude or attitude of land, water, air or space vehicles, e.g. using automatic pilots (drive control systems specially adapted for autonomous road vehicles <u>B60W 60/00</u>)

<u>NOTE</u>

In this main group, it is desirable to add the indexing codes of groups $\{\underline{G05D\ 2101/00} - \underline{G05D\ 2111/00}\}.$

WARNING

Group $\underline{G05D \ 1/00}$ is incomplete pending reclassification of documents from groups $\underline{G05D \ 1/0005}$ - $\underline{G05D \ 1/12}$.

Group <u>G05D 1/00</u> is also impacted by reclassification into groups <u>G05D 1/20</u> - <u>G05D 1/249</u>, <u>G05D 1/40</u> - <u>G05D 1/498</u>, <u>G05D 1/60</u> - <u>G05D 1/6987</u>, <u>G05D 2101/00</u> - <u>G05D 2101/26</u>, <u>G05D 2103/00</u>, <u>G05D 2105/00</u> - <u>G05D 2105/93</u>, <u>G05D 2107/00</u> - <u>G05D 2107/95</u>, <u>G05D 2109/00</u> - <u>G05D 2109/50</u> and <u>G05D 2111/00</u> - <u>G05D 2111/67</u>.

All groups listed in this Warning should be considered in order to perform a complete search.

1/0005 . {with arrangements to save energy}(Frozen) WARNING

Group G05D 1/0005 is no longer used for the classification of documents as of January 1, 2024.

The content of this group is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249,G05D 1/40 - G05D 1/498,G05D 1/60 - G05D 1/6987,G05D 1/80 - G05D 1/87,G05D 2101/00 - G05D 2101/26,G05D 2103/00, G05D 2105/00 - G05D 2105/93,G05D 2107/00 - G05D 2107/95,G05D 2109/00 - G05D 2109/50 and G05D 2111/00 - G05D 2111/67.

All groups listed in this Warning should be considered in order to perform a complete search.

1/0011	• {associated with a remote control arrangement}
(Frozen)	WARNING
	Groups $G05D 1/0011 - G05D 1/005$ are no longer used for the classification of documents as of January 1, 2024.
	The content of these groups is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/498, G05D 1/60 - G05D 1/6987, G05D 1/80 - G05D 1/6987, G05D 2101/00 - G05D 2101/26, G05D 2103/00, G05D 2105/00 - G05D 2105/93, G05D 2107/00 - G05D 2107/95, G05D 2109/00 - G05D 2109/50 and G05D 2111/00 - G05D 2111/67.
	All groups listed in this Warning should be considered in order to perform a complete search.
1/0016 (Frozen)	 {characterised by the operator's input device (input arrangements for computing systems in general <u>G06F 3/00</u>)}
1/0022 (Frozen)	• • {characterised by the communication link (data switching networks in general <u>H04L 12/00</u>)}
1/0027 (Frozen)	 {involving a plurality of vehicles, e.g. fleet or convoy travelling (fleet control of land vehicles from a control room <u>G05D 1/0297</u>; traffic control systems for road vehicles <u>G08G 1/00</u>; for marine craft <u>G08G 3/00</u>; for aircraft <u>G08G 5/00</u>)}
1/0033 (Frozen)	• • {by having the operator tracking the vehicle either by direct line of sight or via one or more cameras located remotely from the vehicle}
1/0038 (Frozen)	 {by providing the operator with simple or augmented images from one or more cameras located onboard the vehicle, e.g. tele-operation (images analyzed by a computer and used for automatic navigation G05D 1/0246)}
1/0044 (Frozen)	• • {by providing the operator with a computer generated representation of the environment of the vehicle, e.g. virtual reality, maps (maps used for automatic navigation <u>G05D 1/0274</u> ; flight directors <u>G01C 23/005</u>)}
1/005 (Frozen)	• • {by providing the operator with signals other than visual, e.g. acoustic, haptic}

1/0055 . {with safety arrangements}

(Frozen)

WARNING Groups G05D 1/0055 - G05D 1/0077 are no longer used for the classification of documents as of January 1, 2024. The content of these groups is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/498. G05D 1/60 - G05D 1/6987, G05D 1/80 - G05D 1/87, <u>G05D 2101/00</u> - <u>G05D 2101/26</u>, <u>G05D 2103/00, G05D 2105/00</u> - <u>G05D 2105/93</u>, G05D 2107/00 - G05D 2107/95, G05D 2109/00 - G05D 2109/50 and <u>G05D 2111/00</u> - <u>G05D 2111/67</u>. All groups listed in this Warning should be

All groups listed in this Warning should be considered in order to perform a complete search.

1/0061	 {for transition from automatic pilot to manual
(Frozen)	pilot and vice versa}

WARNING

Group <u>G05D 1/0061</u> is impacted by reclassification into groups <u>B60W 10/00</u> - <u>B60W 50/16</u>, <u>B60W 60/005 - B60W 60/0061</u>, <u>B60W 2300/00 - B60W 2530/213</u>, <u>B60W 2540/041 - B60W 2540/049</u>, <u>B60W 2552/00 - B60W 2556/65</u>, <u>B60W 2710/00 - B60W 2720/406</u>, and <u>B60W 2754/00 - B60W 2900/00</u>.

All groups listed in this Warning should be considered in order to perform a complete search.

1/0066 . . {for limitation of acceleration or stress}

(Frozen)

- 1/0072 . . {to counteract a motor failure}
- (Frozen) 1/0077
 - • {using redundant signals or controls}
- (Frozen)

(Frozen)

1/0083 . {to help an aircraft pilot in the rolling phase}

WARNING

Group G05D 1/0083 is no longer used for the classification of documents as of January 1, 2024. The content of this group is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/498, G05D 1/40 - G05D 1/498, G05D 1/60 - G05D 1/6987, G05D 1/60 - G05D 1/87, G05D 2101/00 - G05D 2101/26, G05D 2103/00, G05D 2105/00 - G05D 2105/93, G05D 2107/00 - G05D 2107/95, G05D 2109/00 - G05D 2109/50 and G05D 2111/00 - G05D 2111/67.

All groups listed in this Warning should be considered in order to perform a complete search.

1/0088 . (Frozen)	{characterized by the autonomous decision making process, e.g. artificial intelligence, predefined behaviours (using knowledge based models <u>G06N 5/00</u>)}	1/02 Control of position or course in two dimensions (Frozen) WARNING Groups G05D 1/02 – G05D 1/03 are no longer
	WARNING	used for the classification of documents as of January 1, 2024.
	Group G05D 1/0088 is no longer used for the classification of documents as of January 1, 2024. The content of this group is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/498, G05D 1/60 - G05D 1/6987, G05D 2107/00 - G05D 2101/26, G05D 2103/00, G05D 2105/00 - G05D 2105/93, G05D 2107/00 - G05D 2107/95, G05D 2109/00 - G05D 2109/50 and G05D 2109/00 - G05D 2109/50 and G05D 2111/00 - G05D 2111/67. Group G05D 1/0088 is impacted by reclassification into groups B60W 10/00 - B60W 60/00276, B60W 2300/00 - B60W 2530/213, B60W 2552/00 - B60W 2530/213, B60W 2552/00 - B60W 2556/65, B60W 2710/00 - B60W 2720/406 and B60W 2754/00 - B60W 2900/00. All groups listed in this Warning should be considered in order to perform a complete search.	The content of these groups is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/498, G05D 1/60 - G05D 1/6987, G05D 1/80 - G05D 1/87, G05D 2101/00 - G05D 2101/26, G05D 2103/00, G05D 2105/00 - G05D 2105/93, G05D 2109/00 - G05D 2107/95, G05D 2109/00 - G05D 2109/50 and G05D 2111/00 - G05D 2111/67. All groups listed in this Warning should be considered in order to perform a complete search. 1/0202 {specially adapted to aircraft} (<i>Frozen</i>) 1/0204 {to counteract a sudden perturbation, e.g. cross- (<i>Frozen</i>) wind, gust} 1/0206 {specially adapted to water vehicles} (<i>Frozen</i>) 1/0208 {dynamic anchoring} (<i>Frozen</i>) 1/021 {specially adapted to land vehicles} (<i>Frozen</i>)
1/0004		WARNING
1/0094 • (Frozen)	{involving pointing a payload, e.g. camera, weapon, sensor, towards a fixed or moving target}	Group <u>G05D 1/021</u> is impacted by reclassification into groups <u>B60W 10/00</u> - <u>B60W 60/00276</u> ,
	WARNING	<u>B60W 2300/00</u> - <u>B60W 2530/213</u> ,
	Group G05D 1/0094 is no longer used for the classification of documents as of January 1, 2024. The content of this group is being reclassified into groups G05D 1/00, G05D 1/20 - G05D 1/249, G05D 1/40 - G05D 1/498, G05D 1/60 - G05D 1/6987,	B60W 2540/041 - B60W 2540/049, B60W 2552/00 - B60W 2556/65, B60W 2710/00 - B60W 2720/406, and B60W 2754/00 - B60W 2900/00. All groups listed in this Warning should be considered in order to perform a complete search.

 1/0212
 • • • { with means for defining a desired trajectory (involving a plurality of land vehicles

 (Frozen)
 G05D 1/0287)}

<u>G05D 1/80</u> - <u>G05D 1/87</u>,

search.

<u>G05D 2101/00</u> - <u>G05D 2101/26</u>,

<u>G05D 2107/00</u> - <u>G05D 2107/95</u>, <u>G05D 2109/00</u> - <u>G05D 2109/50</u> and <u>G05D 2111/00</u> - <u>G05D 2111/67</u>.

<u>G05D 2103/00, G05D 2105/00</u> - <u>G05D 2105/93</u>,

All groups listed in this Warning should be considered in order to perform a complete

1/0214 (Frozen)	{in accordance with safety or protection criteria, e.g. avoiding hazardous areas (monitoring the location of vehicles within a certain area, e.g. forbidden or allowed areas, in traffic control systems for road vehicles <u>G08G 1/13</u>)}	1 (1 1 (1
	WARNING	1
	Group G05D 1/0214 is impacted by reclassification into groups	(1 1 (1
	<u>B60W 10/00</u> - <u>B60W 60/00276</u> , <u>B60W 2300/00</u> - <u>B60W 2530/213</u> , <u>B60W 2540/041</u> - <u>B60W 2540/049</u> , <u>B60W 2552/00</u> - <u>B60W 2556/65</u> ,	1
	B60W 2710/00 - B60W 2720/406, and B60W 2754/00 - B60W 2900/00.	(1 1 (1
	All groups listed in this Warning should be considered in order to perform a complete search.	(1 1 (1 1
1/0217 (Frozen)	{in accordance with energy consumption, time reduction or distance reduction criteria}	1 (1 1
1/0219 (Frozen)	{ensuring the processing of the whole working surface}	(1 1
1/0221	{involving a learning process}	(1
(Frozen)	WARNING	
	Group <u>G05D 1/0221</u> is impacted by reclassification into groups <u>B60W 10/00</u> - <u>B60W 60/00276</u> ,	1
	B60W 2300/00 - B60W 2530/213, B60W 2540/041 - B60W 2540/049, B60W 2552/00 - B60W 2556/65,	
	<u>B60W 2710/00</u> - <u>B60W 2720/406</u> , and	1
	<u>B60W 2754/00</u> - <u>B60W 2900/00</u> .	(1
	All groups listed in this Warning should be considered in order to perform a complete search.	1. (1
1/0222	-	
1/0223 (Frozen)	{involving speed control of the vehicle (vehicle fittings for automatically	1
(<u>-</u>)	controlling, i.e. preventing speed from	(1
	exceeding an arbitrarily established velocity or maintaining speed at a particular	1
	velocity of mannaming speed at a particular velocity, as selected by the vehicle operator	(1
	<u>B60K 31/00</u>)}	1
	WARNING	1.
	Group G05D 1/0223 is impacted	(1
	by reclassification into groups	1
	<u>B60W 10/00</u> - <u>B60W 60/00276</u> ,	(1
	$\frac{B60W}{2540/00} - \frac{B60W}{2530/213},$	1
	B60W 2540/041 - B60W 2540/049, B60W 2552/00 - B60W 2556/65,	(-
	$\frac{B60W}{2710/00} - \frac{B60W}{2720/406}, \text{ and} \\ \frac{B60W}{2754/00} - \frac{B60W}{2900/00}.$	
	All groups listed in this Warning should be considered in order to perform a complete search.	1 (1
1/0225 (Frozen)	{involving docking at a fixed facility, e.g. base station or loading bay (parking aids <u>B62D 15/027</u>)}	1
	using mechanical sensing means, e.g. for ensing treated area}	(1
(Frozen) so $1/0229$ $(Frozen)$	{in combination with fixed guiding means}	
e.		

1/0231 {using optical position detecting means
(Frozen) (position-fixing by using electromagnetic
waves other than radio waves, e.g. optical
position detecting means <u>G01S 5/16</u>)}
1/0234 {using optical markers or beacons (optical beacons per se G01S 1/70)}
$1/0236$ {in combination with a laser (lasers per se
(<i>Frozen</i>) H01S)}
1/0238 { using obstacle or wall sensors
(<i>Frozen</i>) ($\underline{G05D 1/0246}$ and $\underline{G05D 1/0289}$ take
precedence; lidar systems designed for anti-
collision purposes G01S 17/93)}
1/024 {in combination with a laser (lasers per se
(Frozen) <u>H01S</u>)
1/0242 {using non-visible light signals, e.g. IR or
(Frozen) UV signals}
1/0244 {using reflecting strips}
(<i>Frozen</i>) 1/0246 {using a video camera in combination with
(<i>Frozen</i>) image processing means}
1/0248 {in combination with a laser (lasers per se
(<i>Frozen</i>) <u>H01S</u>)}
1/0251 {extracting 3D information from a
(Frozen) plurality of images taken from different
locations, e.g. stereo vision (stereoscopic
image analysis <u>H04N 13/00</u> ; depth
recovery from images <u>G06T 7/593</u>)}
1/0253 {extracting relative motion information
(<i>Frozen</i>) from a plurality of images taken successively, e.g. visual odometry, optical
flow (determining position or orientation
from images <u>G06T 7/70</u>)}
1/0255 {using acoustic signals, e.g. ultra-sonic singals
(Frozen) (sonar systems designed for anti-collision
purposes <u>G01S 15/93</u>)}
1/0257 {using a radar (radar systems designed for
(Frozen) anti-collision purposes between land vehicles or between land vehicle and fixed obstacles
GOIS 13/931)
1/0259 {using magnetic or electromagnetic means}
(Frozen)
1/0261 {using magnetic plots}
(Frozen)
1/0263 { using magnetic strips }
(Frozen)
1/0265 {using buried wires}
(Frozen)
1/0268 {using internal positioning means}
(<i>Frozen</i>) 1/027 {comprising intertial navigation means,
<i>(Frozen)</i> e.g. azimuth detector (inertial navigation
<u>G01C 21/16;</u> inertial navigation combined
with non-inertial navigation instruments
<u>G01C 21/165</u>)}
1/0272 {comprising means for registering the
(<i>Frozen</i>) travel distance, e.g. revolutions of wheels
(measuring distance traversed on the
ground by vehicles, e.g. using odometers G01C 22/00)}
1/0274 { using mapping information stored in a
(<i>Frozen</i>) memory device (navigation using map-
matching <u>G01C 21/30</u>)}
<u> </u>

1/0276 (Frozen) 1/0278	 {using signals provided by a source external to the vehicle (involving a plurality of vehicles <u>G05D 1/0287</u>; automatically controlling vehicle speed responsive to externally generated signals <u>B60K 31/0058</u>)} {using satellite positioning signals, e.g. <u>GDS</u>)
(Frozen) 1/028 (Frozen)	GPS} {using a RF signal}
1/0282 (Frozen)	•••• {generated in a local control room}
1/0285 (Frozen)	• • • { using signals transmitted via a public communication network, e.g. GSM network }
1/0287 (Frozen)	 • {involving a plurality of land vehicles, e.g. fleet or convoy travelling (traffic control systems for road vehicles <u>G08G 1/00</u>, particularly anticollision systems <u>G08G 1/16</u>)}
1/0289 (Frozen)	{with means for avoiding collisions between vehicles (vehicle fittings for automatically controlling speed including means for detecting potential obstacles <u>B60K 31/0008</u> ; avoiding obstacles by action on the steering system <u>B62D</u> ; radar, sonar, lidar systems designed for anti-collision purposes <u>G01S 13/93</u> , <u>G01S 15/93</u> , <u>G01S 17/93</u>)}
1/0291 (Frozen)	 {Fleet control (monitoring fleets in traffic control systems for road vehicles <u>G08G 1/127, G08G 1/127</u>)}
1/0293	{Convoy travelling}
(Frozen)	
1/0295 (Frozen)	{by at least one leading vehicle of the fleet}
1/0297	• • • • {by controlling means in a control room}
(Frozen)	
1/03 (Frozen)	 using near-field transmission systems, e.g. inductive-loop type {(G05D 1/021 and subgroups take precedence)}
1/04	• Control of altitude or depth
(Frozen)	WARNING
	Groups $\underline{G05D 1/04} - \underline{G05D 1/0692}$ are no longer used for the classification of documents as of January 1, 2024.
	The content of these groups is
	being reclassified into groups
	<u>G05D 1/00, G05D 1/20</u> - <u>G05D 1/249,</u> <u>G05D 1/40</u> - <u>G05D 1/498,</u>
	$\frac{G05D 1/60}{G05D 1/6987},$
	$\frac{\text{G05D 1/80}}{\text{G05D 2101/00}} - \frac{\text{G05D 1/87}}{\text{G05D 2101/06}}$
	<u>G05D 2101/00</u> - <u>G05D 2101/26</u> , <u>G05D 2103/00</u> , <u>G05D 2105/00</u> - <u>G05D 2105/93</u> ,
	<u>G05D 2107/00</u> - <u>G05D 2107/95</u> , <u>G05D 2109/00</u> - <u>G05D 2109/50</u> and
	$\frac{G05D \ 2111/00}{G05D \ 2111/67}$
	All groups listed in this Warning should be considered in order to perform a complete search.
1/042 (Frozen)	• • {specially adapted for aircraft}
1/044	{during banks}
(Frozen) 1/046	
1/046 (Frozen)	• • {to counteract a perturbation, e.g. gust of wind}

1/048 (Frozen)	•	•	{spe	cially adapted for water vehicles}
1/06 (<i>Frozen</i>)	•	•	Rate	of change of altitude or depth
1/0607	•	•	• {s	pecially adapted for aircraft}
(Frozen) 1/0615	•	•		{to counteract a perturbation, e.g. gust of
(Frozen) 1/0623	•	•		wind }{by acting on the pitch}
(Frozen) 1/063	•	•	•••	• {by acting on the motors}
(Frozen) 1/0638	•	•	•••	• {by combined action on the pitch and on
(Frozen) 1/0646	•	•	•••	the motors} {to follow the profile of undulating ground}
(Frozen) 1/0653	•	•	•••	{during a phase of take-off or landing}
(Frozen) 1/0661	•	•		• {specially adapted for take-off}
(Frozen) 1/0669	•	•		• • {specially adapted for vertical take-off}
(Frozen) 1/0676	•	•		• {specially adapted for landing}
(Frozen) 1/0684	•	•		• • {on a moving platform, e.g. aircraft
(Frozen) 1/0688	•	•		carrier} {Emergency descent}
(Frozen) 1/0692	•	•	• {s	pecially adapted for under-water vehicles}
(Frozen) 1/08		C		l of attitude, i.e. control of roll, pitch, or yaw
			ontro	
	•			
(Frozen)	•			NING
	•		ARM Gro used	NING ups G05D 1/08 – G05D 1/0891 are no longer d for the classification of documents as of
	•		ARI Gro useo Jani	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024.
	•		ARM Gro used Janu The	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is
	•		ARM Gro used Janu The beir	NING ups G05D 1/08 – G05D 1/0891 are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups
	•		ARM Gro used Janu The bein <u>G05</u>	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups <u>5D 1/00, G05D 1/20</u> - <u>G05D 1/249</u> ,
	•		ARM Gro used Janu The bein <u>G03</u>	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups <u>5D 1/00, G05D 1/20</u> - <u>G05D 1/249,</u> <u>5D 1/40</u> - <u>G05D 1/498,</u>
	•		ARM Gro used Janu The beir <u>G03</u> <u>G03</u>	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups <u>5D 1/00, G05D 1/20</u> - <u>G05D 1/249,</u> <u>5D 1/40</u> - <u>G05D 1/498,</u> <u>5D 1/60</u> - <u>G05D 1/6987,</u>
			ARM Gro used Janu The bein <u>G03</u> <u>G03</u> <u>G03</u>	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups <u>5D 1/00, G05D 1/20</u> - <u>G05D 1/249,</u> <u>5D 1/40</u> - <u>G05D 1/498,</u> <u>5D 1/60</u> - <u>G05D 1/6987,</u> <u>5D 1/80</u> - <u>G05D 1/87,</u>
			ARM Groused Janu The bein <u>G05</u> <u>G05</u> <u>G05</u> <u>G05</u>	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups <u>5D 1/00, G05D 1/20</u> - <u>G05D 1/249,</u> <u>5D 1/40</u> - <u>G05D 1/498,</u> <u>5D 1/60</u> - <u>G05D 1/6987,</u>
			ARI Groused Janu The bein G03	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups <u>5D 1/00, G05D 1/20 - G05D 1/249,</u> <u>5D 1/40 - G05D 1/498,</u> <u>5D 1/60 - G05D 1/6987,</u> <u>5D 1/80 - G05D 1/87,</u> <u>5D 2101/00 - G05D 2101/26,</u>
	•		Grou Used Jami The bein G02 G03 G04	NING ups $G05D 1/08 - G05D 1/0891$ are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/87, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2107/95, 5D 2109/00 - G05D 2109/50 and
	-		Grou Used Jami The bein G02 G03 G04	NING ups $G05D 1/08 - G05D 1/0891$ are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/87, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2107/95,
	-		Grou used Jam The bein <u>G02</u> <u>G03</u> <u>G04</u>	NING ups $\underline{G05D 1/08} - \underline{G05D 1/0891}$ are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups $\underline{5D 1/00}, \underline{G05D 1/20} - \underline{G05D 1/249},$ $\underline{5D 1/40} - \underline{G05D 1/20} - \underline{G05D 1/249},$ $\underline{5D 1/40} - \underline{G05D 1/498},$ $\underline{5D 1/60} - \underline{G05D 1/6987},$ $\underline{5D 1/80} - \underline{G05D 1/87},$ $\underline{5D 2101/00} - \underline{G05D 2101/26},$ $\underline{5D 2103/00}, \underline{G05D 2105/00} - \underline{G05D 2105/93},$ $\underline{5D 2109/00} - \underline{G05D 2107/95},$ $\underline{5D 2111/00} - \underline{G05D 2111/67}.$ groups listed in this Warning should be
	-		Grou used Jam The bein <u>G02</u> <u>G03</u> <u>G04</u>	NING ups $\underline{G05D 1/08} - \underline{G05D 1/0891}$ are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups $\underline{5D 1/00}, \underline{G05D 1/20} - \underline{G05D 1/249},$ $\underline{5D 1/40} - \underline{G05D 1/20} - \underline{G05D 1/249},$ $\underline{5D 1/40} - \underline{G05D 1/498},$ $\underline{5D 1/60} - \underline{G05D 1/6987},$ $\underline{5D 1/80} - \underline{G05D 1/87},$ $\underline{5D 2101/00} - \underline{G05D 2101/26},$ $\underline{5D 2103/00}, \underline{G05D 2105/00} - \underline{G05D 2105/93},$ $\underline{5D 2107/00} - \underline{G05D 2107/95},$ $\underline{5D 2109/00} - \underline{G05D 2101/26},$ $\underline{5D 2111/00} - \underline{G05D 2111/67}.$ groups listed in this Warning should be sidered in order to perform a complete
(Frozen) 1/0808		w	Grou used Jann The bein GO2 GO2 GO2 GO2 GO2 GO2 GO2 GO2 GO2 GO2	NING ups $\underline{G05D 1/08} - \underline{G05D 1/0891}$ are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups $\underline{5D 1/00}, \underline{G05D 1/20} - \underline{G05D 1/249},$ $\underline{5D 1/40} - \underline{G05D 1/20} - \underline{G05D 1/249},$ $\underline{5D 1/40} - \underline{G05D 1/498},$ $\underline{5D 1/60} - \underline{G05D 1/6987},$ $\underline{5D 1/80} - \underline{G05D 1/87},$ $\underline{5D 2101/00} - \underline{G05D 2101/26},$ $\underline{5D 2103/00}, \underline{G05D 2105/00} - \underline{G05D 2105/93},$ $\underline{5D 2107/00} - \underline{G05D 2107/95},$ $\underline{5D 2109/00} - \underline{G05D 2101/26},$ $\underline{5D 2111/00} - \underline{G05D 2111/67}.$ groups listed in this Warning should be sidered in order to perform a complete
(Frozen) 1/0808 (Frozen) 1/0816		<u>w</u>	ARN Groo used Jan The beir <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>G</u> <u>G</u> <u>GOS</u> <u>GOS</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u>	NING ups $G05D 1/08 - G05D 1/0891$ are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/6987, 5D 1/80 - G05D 2105/00 - G05D 2105/03, 5D 2101/00 - G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2105/00 - G05D 2105/93, 5D 2109/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67.groups listed in this Warning should be sidered in order to perform a complete rch.
(Frozen) 1/0808 (Frozen)	•	<u>w</u>	ARN Groo used Jan The beir <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>GOS</u> <u>G</u> <u>G</u> <u>GOS</u> <u>GOS</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u> <u>G</u>	NING ups <u>G05D 1/08</u> – <u>G05D 1/0891</u> are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups $5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 2105/00 - G05D 2105/00, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability}$
(Frozen) 1/0808 (Frozen) 1/0816 (Frozen) 1/0825	· · · · · · · · · · · · · · · · · · ·	<u>w</u>	ARN Grooused Jann The bein GO2 GO2 <td>NING ups $G05D 1/08 - G05D 1/0891$ are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/298, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/87, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2107/95, 5D 2109/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability}</td>	NING ups $G05D 1/08 - G05D 1/0891$ are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/298, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/87, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2107/95, 5D 2109/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability}
(Frozen) 1/0808 (Frozen) 1/0816 (Frozen) 1/0825 (Frozen) 1/0833	· · · · · · · · · · · · · · · · · · ·	<u>w</u>	Grouse Janu The bein GO2 GO3 GO3 GO4 Ton See	NING ups $G05D 1/08 - G05D 1/0891$ are no longer d for the classification of documents as of uary 1, 2024. content of these groups is ng reclassified into groups SD 1/00, G05D 1/20 - G05D 1/249, SD 1/40 - G05D 1/298, SD 1/40 - G05D 1/498, SD 1/60 - G05D 1/6987, SD 1/80 - G05D 1/87, SD 2101/00 - G05D 2101/26, SD 2103/00, G05D 2105/00 - G05D 2105/93, SD 2107/00 - G05D 2109/50 and SD 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability} {using mathematical models}
(Frozen) 1/0808 (Frozen) 1/0816 (Frozen) 1/0825 (Frozen) 1/0833 (Frozen) 1/0841		<u>w</u>	Grouse Janu The bein GO2 GO3 GO3 GO4 The GO3 GO4 GO5 GO3 GO4 GO5 GO4 GO5	NING ups G05D 1/08 – G05D 1/0891 are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/87, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability} {using mathematical models} {using limited authority control} {to prevent a coupling between different
(Frozen) 1/0808 (Frozen) 1/0816 (Frozen) 1/0825 (Frozen) 1/0833 (Frozen) 1/0841 (Frozen)	· · · · · · · · · · · · · · · · · · ·	<u>w</u>	Grouse Janu The bein GO2 GO3 GO3 GO4 Inno Inno Inno Inno Inno Inno Inno Inno Inno	NING ups G05D 1/08 – G05D 1/0891 are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/60 - G05D 1/6987, 5D 1/80 - G05D 1/6987, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability} {using mathematical models} {using limited authority control} {to prevent a coupling between different modes}
(Frozen) 1/0808 (Frozen) 1/0816 (Frozen) 1/0833 (Frozen) 1/0841 (Frozen) 1/0841 (Frozen) 1/0841		<u>w</u>	Grouse Jann The bein G02 G03 G04 G05 G02 G03 G04 G05	NING ups G05D 1/08 – G05D 1/0891 are no longer d for the classification of documents as of uary 1, 2024. a content of these groups is ag reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/40 - G05D 1/6987, 5D 1/80 - G05D 1/6987, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability} {using mathematical models} {using limited authority control} {to prevent a coupling between different modes} {to ensure coordination between different movements} pecially adapted for vertical take-off of
(Frozen) 1/0808 (Frozen) 1/0816 (Frozen) 1/0825 (Frozen) 1/0833 (Frozen) 1/0841 (Frozen) 1/085 (Frozen)	· · · · · · · · · · · · · · · · · · ·	<u>w</u>	Grouse Jann The bein G02 G03 G04 G05 G02 G03 G04 G05	NING ups G05D 1/08 – G05D 1/0891 are no longer d for the classification of documents as of uary 1, 2024. c content of these groups is ng reclassified into groups 5D 1/00, G05D 1/20 - G05D 1/249, 5D 1/40 - G05D 1/498, 5D 1/40 - G05D 1/6987, 5D 1/80 - G05D 1/6987, 5D 2101/00 - G05D 2101/26, 5D 2103/00, G05D 2105/00 - G05D 2105/93, 5D 2107/00 - G05D 2107/95, 5D 2109/00 - G05D 2109/50 and 5D 2111/00 - G05D 2111/67. groups listed in this Warning should be sidered in order to perform a complete rch. cially adapted for aircraft} o ensure stability} {using mathematical models} {using limited authority control} {to prevent a coupling between different modes} {to ensure coordination between different movements}

1/00/00	
1/0866 (Frozen)	• • {specially adapted to captive aircraft}
1/0875	• • {specially adapted to water vehicles}
(Frozen)	• (specially adapted to water vehicles)
1/0891 (Frozen)	• • {specially adapted for land vehicles}
1/10	. Simultaneous control of position or course in three
(Frozen)	dimensions ($\underline{G05D \ 1/12}$ takes precedence)
	WARNING
	Groups <u>G05D 1/10</u> – <u>G05D 1/108</u> are no longer
	used for the classification of documents as of
	January 1, 2024.
	The content of these groups is
	being reclassified into groups
	G05D 1/00, G05D 1/20 - G05D 1/249,
	<u>G05D 1/40</u> - <u>G05D 1/498</u> , <u>G05D 1/60</u> - <u>G05D 1/6987</u> ,
	$\frac{G05D 1/80}{G05D 1/80} - \frac{G05D 1/87}{G05D 1/87},$
	$\frac{G05D}{G05D} \frac{1}{2101} \frac{1}{00} - \frac{G05D}{2101} \frac{1}{2101} \frac{1}{26},$
	<u>G05D 2103/00, G05D 2105/00</u> - <u>G05D 2105/93,</u>
	<u>G05D 2107/00</u> - <u>G05D 2107/95</u> ,
	<u>G05D 2109/00</u> - <u>G05D 2109/50</u> and
	<u>G05D 2111/00</u> - <u>G05D 2111/67</u> .
	All groups listed in this Warning should be
	considered in order to perform a complete
	search.
1/101	• • {specially adapted for aircraft}
(Frozen)	
1/102	• • • {specially adapted for vertical take-off of
(Frozen)	aircraft}
1/104 (Frozen)	• • • {involving a plurality of aircrafts, e.g. formation flying (traffic control systems for
(Frozen)	aircraft <u>G08G 5/00</u>)}
1/105	• • {specially adapted for unpowered flight, e.g.
(Frozen)	glider, parachuting, forced landing (parachutes
(- /	per se <u>B64D 17/00</u>)}
1/106	• • • {Change initiated in response to external
(Frozen)	conditions, e.g. avoidance of elevated terrain or
	of no-fly zones}
1/1062	• • • {specially adapted for avoiding bad weather
(Frozen)	conditions}
1/1064	(specially adapted for avoiding collisions
(Frozen) 1/107	with other aircraft}• {specially adapted for missiles}
(<i>Frozen</i>)	• (specially adapted for missiles)
1/102 <i>en</i>)	• • • {animated with a rolling movement}
(Frozen)	• • • {annuace with a forming movement}
(1.02011)	

1/12	•	Target-seeking control
(Frozen)		WADNING

1/20

WARNING Group G05D 1/12 is no longer used for the classification of documents as of January 1, 2024. The content of this group is being reclassified into groups <u>G05D 1/00, G05D 1/20</u> - <u>G05D 1/249</u>, G05D 1/40 - G05D 1/498, G05D 1/60 - G05D 1/6987, <u>G05D 1/80</u> - <u>G05D 1/87</u>, <u>G05D 2101/00</u> - <u>G05D 2101/26</u>, <u>G05D 2103/00, G05D 2105/00</u> - <u>G05D 2105/93</u>, <u>G05D 2107/00</u> - <u>G05D 2107/95</u>, G05D 2109/00 - G05D 2109/50 and <u>G05D 2111/00</u> - <u>G05D 2111/67</u>. All groups listed in this Warning should be considered in order to perform a complete search. • Control system inputs WARNING

Groups <u>G05D 1/20</u> - <u>G05D 1/249</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search.

1/22	Command input arrangements
1/221	Remote-control arrangements
1/222	• • • • operated by humans
1/223	Command input arrangements on the
	remote controller, e.g. joysticks or touch
	screens
1/2232	••••• {Touch screens}
1/2234	••••• {Neurological interfaces}
1/2235	• • • • {involving the operator tracking the
	vehicle by direct line of sight}
1/224	Output arrangements on the remote
	controller, e.g. displays, haptics or
	speakers
1/2242	••••• {Haptics}
1/2243	••••• {Acoustic}
1/2244	••••• {Optic}
1/2245	••••• {providing the operator with a purely
	computer-generated representation of
	the environment of the vehicle, e.g.
	virtual reality}
1/2246	••••••••••• (displaying a map of the
	environment}
1/2247	••••• {providing the operator with simple
	or augmented images from one or
	more cameras}
1/2248	{the one or more cameras located
	remotely from the vehicle}
1/2249	••••••••• {using augmented reality}
1/225	operated by off-board computers
1/226	Communication links with the remote-
	control arrangements
1/2265	•••• {involving protocol translation}

1/227	• • • Handing over between remote control and on-board control; Handing over between remote control arrangements
1/2272	• • • • {in response to remote override by external entities, e.g. authorities}
1/2274	•••• {in response to the communication link being lost, degraded or compromised, e.g. anti-spoofing}
1/2276	•••• { for keeping or re-establishing line of sight }
1/2278	•••• {for returning to designated location}
1/2279	••••• {involving allocation of control between two or more remote operators, e.g. tele- assistance}
1/228	Command input arrangements located on-board unmanned vehicles
1/2285	• • • using voice or gesture commands
1/2287	• • • { using an external force applied to the vehicle }
1/229	Command input data, e.g. waypoints
1/2295	• • • • {defining restricted zones, e.g. no-flight zones or geofences}
1/2297	• • • {positional data taught by the user, e.g. paths (G05D 1/2295 takes precedence)}
1/24	• Arrangements for determining position or orientation
1/241	• • • Means for detecting physical contact, e.g. touch sensors or bump sensors
1/242	Means based on the reflection of waves
	generated by the vehicle (using passive
	navigation aids external to the vehicle <u>G05D 1/244;</u> using signals provided by
	artificial sources external to the vehicle
	<u>G05D 1/247</u>)
1/2424	• • • • {for monitoring a plurality of zones}
1/2427	• • • • {for monitoring a zone of adjustable size or form}
1/243	• • • Means capturing signals occurring naturally
	from the environment, e.g. ambient optical,
	acoustic, gravitational or magnetic signals (using passive navigation aids external to
	the vehicle <u>G05D 1/244</u> ; using signals from
	positioning sensors located off-board the
	vehicle <u>G05D 1/249</u>)
1/2435	• • • • {Extracting 3D information}
1/2437	{Extracting relative motion information}
1/244	using passive navigation aids external to the
	vehicle, e.g. markers, reflectors or magnetic means
1/2446	• • • { the passive navigation aids having encoded
	information, e.g. QR codes or ground control points}
1/245	using dead reckoning
1/246	• • • using environment maps, e.g. simultaneous
	localisation and mapping [SLAM]
1/2462	• • • {using feature-based mapping}
1/2464	• • • {using an occupancy grid}
1/2465 1/2467	 {using a 3D model of the environment} {using a semantic description of the
1/240/	environment}
1/2469	• • • • {using a topologic or simplified map}
1/247	using signals provided by artificial sources
	external to the vehicle, e.g. navigation beacons
1/248	generated by satellites, e.g. GPS

1/249	from positioning sensors located off-board
1/40	the vehicle, e.g. from cameras • Control within particular dimensions
1/40	WARNING
	Groups <u>G05D 1/40</u> - <u>G05D 1/498</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u> .
	All groups listed in this Warning should be considered in order to perform a complete search.
1/43	• Control of position or course in two dimensions
1/435	• • resulting in a change of level, e.g. negotiating lifts or stairs
1/437	 for aircraft during their ground movement {, e.g. taxiing}
1/439	• • • • {on the runway during take-off or landing}
1/46	• • Control of position or course in three dimensions
1/461	• • for unpowered vehicles, e.g. gliders or parachutes
1/467	• • • for movement inside a confined volume, e.g. indoor flying
1/48	. Control of altitude or depth
1/482	• • • {utilising or compensating for ground effect}
1/484	• • • {during banking manoeuvres}
1/485	Control of rate of change of altitude or depth
1/49	• Control of attitude, i.e. control of roll, pitch or yaw
1/495	• • • to ensure stability
1/496	• • • {compensating for coupling between different axes of movement}
1/498	• • {involving adjustment of the relative position of the centre of gravity of the vehicle}
	of the centre of gravity of the vehicle)
1/60	• Intended control result
1/60	- · · ·
1/60	Intended control result <u>WARNING</u>
1/60	. Intended control result
1/60	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are
1/60	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 –
1/60 1/606	 Intended control result WARNING Groups <u>G05D 1/60</u> - <u>G05D 1/6987</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete
	 Intended control result WARNING Groups <u>G05D 1/60</u> - <u>G05D 1/6987</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search.
	 Intended control result WARNING Groups <u>G05D 1/60</u> - <u>G05D 1/6987</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping <u>G05D 1/611</u>) Station keeping, e.g. for hovering or dynamic
1/606	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection
1/606 1/611	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards
1/606 1/611	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or
1/606 1/611	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding
1/606 1/611	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or
1/606 1/611	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween G05D 1/693;
1/606 1/611	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween G05D 1/693; arrangements for reacting to or preventing system
1/606 1/611 1/617	 Intended control result WARNING Groups <u>G05D 1/60</u> - <u>G05D 1/6987</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping <u>G05D 1/611</u>) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween <u>G05D 1/693</u>; arrangements for reacting to or preventing system or operator failure <u>G05D 1/80</u>) Example to the exposure of a vehicle to
1/606 1/611 1/617 1/618	 Intended control result WARNING Groups <u>G05D 1/60</u> - <u>G05D 1/6987</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping <u>G05D 1/611</u>) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween <u>G05D 1/693</u>; arrangements for reacting to or preventing system or operator failure <u>G05D 1/80</u>) . {for cargo or occupants} . {Minimising the exposure of a vehicle to threats, e.g. avoiding interceptors}
1/606 1/611 1/617 1/618	 Intended control result WARNING Groups <u>G05D 1/60</u> - <u>G05D 1/6987</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping <u>G05D 1/611</u>) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween <u>G05D 1/693</u>; arrangements for reacting to or preventing system or operator failure <u>G05D 1/80</u>) Example to the exposure of a vehicle to
1/606 1/611 1/617 1/618 1/619	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween G05D 1/693; arrangements for reacting to or preventing system or operator failure G05D 1/80) {for cargo or occupants} {Minimising the exposure of a vehicle to threats, e.g. avoiding interceptors} {responding to weather conditions, e.g. storms or wind shear} Obstacle avoidance (predicting or avoiding
1/606 1/611 1/617 1/618 1/619 1/621	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween G05D 1/693; arrangements for reacting to or preventing system or operator failure G05D 1/80) {for cargo or occupants} {Minimising the exposure of a vehicle to threats, e.g. avoiding interceptors} {responding to weather conditions, e.g. storms or wind shear} Obstacle avoidance (predicting or avoiding probable or impending collision of road
1/606 1/611 1/617 1/618 1/619 1/621	 Intended control result WARNING Groups G05D 1/60 - G05D 1/6987 are incomplete pending reclassification of documents from groups G05D 1/00 – G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Compensating for or utilising external environmental conditions, e.g. wind or water currents (station keeping G05D 1/611) Station keeping, e.g. for hovering or dynamic anchoring Safety or protection, e.g. defining protection zones around obstacles or avoiding hazards (arrangements for controlling the position or course of two or more vehicles for avoiding collisions therebetween G05D 1/693; arrangements for reacting to or preventing system or operator failure G05D 1/80) {for cargo or occupants} {Minimising the exposure of a vehicle to threats, e.g. avoiding interceptors} {responding to weather conditions, e.g. storms or wind shear} Obstacle avoidance (predicting or avoiding

1/628	• • • following the obstacle profile, e.g. a wall or undulated terrain
1/(22	
1/633	Dynamic obstacles
1/637	• • • {using safety zones of adjustable size or
1/620	shape}
1/639	• • Resolving or avoiding being stuck or
1/640	obstructed
1/642	• • • {involving obstacle removal, e.g. opening
1 / 6 4 4	doors or pushing furniture}
1/644	• • Optimisation of travel parameters, e.g. of energy
1 / 6 4 4 5	consumption, journey time or distance
1/6445	• • • {for optimising payload operation, e.g. camera
1 / - 1 -	or spray coverage }
1/645	• • • {Vehicle-induced nuisance abatement, e.g.
	minimising noise or visual impact}
1/646	• Following a predefined trajectory, e.g. a line
	marked on the floor or a flight path
1/648	• Performing a task within a working area or space,
	e.g. cleaning
1/6482	• • • {by dividing the whole area or space in sectors
	to be processed separately}
1/6484	• • • {by taking into account parameters or
	characteristics of the working area or space,
	e.g. size or shape}
1/6485	• • • {by taking into account surface type, e.g.
	carpeting }
1/6486	• • • {by taking into account surface condition,
	e.g. soiled}
1/65	• • Following a desired speed profile
1/651	• • • {with controlled time of arrival at target points,
	e.g. 4D navigation}
1/652	• Take-off (delivering or retrieving payloads
	<u>G05D 1/667</u>)
1/654	• Landing (docking at a base station G05D 1/661)
1/6542	••• {on a moving platform, e.g. aircraft carrier}
1/6545	• • {during descent or approach phase}
1/6546	• • {Emergency landing}
1/6548	• • {Aborted landing, e.g. go-around}
1/656	• Interaction with payloads or external entities
1/661	• • Docking at a base station (delivering or
1/001	retrieving payloads <u>G05D 1/667</u>)
1/663	• • • {docking at a moving base station}
1/665	 . {Releasing payloads, e.g. parachutes}
1/667	
	e e
1/672	• • Positioning of towed, pushed or suspended
1/670	
1/678	implements, e.g. ploughs
	for tethered vehicles (positioning towed,
1/692	• • for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>)
1/683	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base
	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>)
1/683 1/686	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect
	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or
	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets
	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position
1/686	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>)
	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving
1/686	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving targets (positioning towed, pushed or
1/686 1/689	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving targets (positioning towed, pushed or suspended implements <u>G05D 1/672</u>)
1/686 1/689 1/6895	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving targets (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) {the payload being a manipulator arm}
1/686 1/689	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving targets (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) {the payload being a manipulator arm} Coordinated control of the position or course of
1/686 1/689 1/6895 1/69	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving targets (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) {the payload being a manipulator arm} Coordinated control of the position or course of two or more vehicles
1/686 1/689 1/6895	 for tethered vehicles (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) Intercepting moving targets (docking at a base station <u>G05D 1/661</u>) Maintaining a relative position with respect to moving targets, e.g. following animals or humans (for pointing payloads towards targets <u>G05D 1/689</u>; involving controlling the position or course of two or more vehicles <u>G05D 1/69</u>) Pointing payloads towards fixed or moving targets (positioning towed, pushed or suspended implements <u>G05D 1/672</u>) {the payload being a manipulator arm} Coordinated control of the position or course of

1/695	• • for maintaining a fixed relative position of the vehicles, e.g. for convoy travelling or formation flight
1/696	• • • { involving a plurality of vehicles coupled together }
1/697	• • • for rendezvous of two or more vehicles, e.g. for in-flight refuelling (docking at a base station <u>G05D 1/661</u>)
1/698	Control allocation
1/6983	• • • • {by distributed or sequential control}
1/6985	• • • {using a lead vehicle, e.g. primary-secondary
1/6987	arrangements }•••• {by centralised control off-board any of the vehicles }
1/80	• Arrangements for reacting to or preventing system or operator failure (handing over between remote control and on-board control, or handing over
	between remote control arrangements G05D 1/227)
	WARNING
	Groups <u>G05D 1/80</u> – <u>G05D 1/87</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u> .
	All groups listed in this Warning should be considered in order to perform a complete search.
1/81	• Handing over between on-board automatic and on-board manual control
1/815	• • {to recover from unusual attitude conditions}
1/817	• • • {to recover from pilot incapacitation}
1/82	• Limited authority control, e.g. enforcing a flight envelope (limitation of acceleration or structural stress <u>G05D 1/83</u>)
1/83	Limitation of acceleration or structural stress
1/85	• Fail-safe operations, e.g. limp home mode
1/852	• • {in response to low power or low fuel conditions}
1/854	• • • {in response to motor or actuator failures}
1/857	• • • {in response to sensor failures}
1/86	• • Monitoring the performance of the system, e.g.
1/07	alarm or diagnosis modules
1/87	• • using redundant control arrangements
3/00	Control of position or direction (G05D 1/00 takes precedence; numerical control to execute positioning G05B 19/18)
3/10	• without using feedback
3/105	• • {Solar tracker}
3/12	• using feedback
3/121	• • {using synchromachines (selsyns)}
3/122	• • • {without modulation}
3/124	• • • {with modulation}
3/125	• {using discrete position sensor}
3/127	• • { with electrical contact }
3/128	• { using clutch or brake }
3/14 3/1409	 using an analogue comparing device { with dc amplifier chain }
3/1409	 {with ac amplifier chain} {with ac amplifier chain}
3/1418	 {with ac amplifier chain} {with non-linear amplifier chain}
3/1427	• • {with fine or coarse devices}
3/1445	• • • {with a plurality of loops}
3/1454	{using models or predicting devices}
3/1463	{using PID devices}

3/1472	• • • {with potentiometer}
3/1481	• • • {with discrete position sensor}
3/149	• • • {with clutch or brake}
3/16	• • • whose output amplitude can only take a number of discrete values (G05D 3/18 takes precedence)
3/165	• • • {using clutch or brake}
3/18	delivering a series of pulses
3/183	• • • • {using stepping motor}
3/186	• • • {using clutch or brake}
3/20	• • using a digital comparing device
3/203	• • {using fine or coarse devices}
3/206	• • • {using clutch or brakes}
5/00	Control of dimensions of material
5/02	• of thickness, e.g. of rolled material (of specific
5/02	materials <u>B21B</u> , <u>B29C</u> , <u>B32B</u> , <u>C03B</u> , <u>D21F</u>)
5/03	• characterised by the use of electric means
5/04	• of the size of items, e.g. of particles
5/06	• • characterised by the use of electric means
7/00	Control of flow (level control <u>G05D 9/00</u> ; control of flow ratio <u>G05D 11/00</u>)
	NOTE
	In groups <u>G05D 7/0629</u> - <u>G05D 7/0694</u> , the last place priority rule is applied, i.e. at each hierarchical level, in the absence of an indication to the contrary, classification is made in the last appropriate place.
7/005	• {characterised by the use of auxiliary non-electric power combined with the use of electric means}
7/01	 without auxiliary power
7/0106	 the sensing element being a flexible member, e.g. bellows, diaphragm, capsule}
7/0113	• • { the sensing element acting as a valve }
7/012	• • • {the sensing element being deformable and acting as a valve}
7/0126	• • {the sensing element being a piston or plunger associated with one or more springs}
7/0133	• • • {within the flow-path}
7/014	• • • {using sliding elements}
7/0146	• • {the in-line sensing element being a piston or float without flexible member or spring}
7/0153	• • • {using slidable elements}
7/016	• • • {the sensing element being a ball}
7/0166	• • {the sensing element being a float or a ball placed outside the flow path to be controlled}
7/0173	• {using pivoting sensing element acting as a valve mounted within the flow-path}
7/018	• • {using rotary sensing element}
7/0186	• • {without moving parts}
7/0193	• • {using hydraulic or pneumatic amplifiers, relays or transmitters}
7/03	 with auxiliary non-electric power {(<u>G05D 7/005</u> takes precedence)}
7/06	• characterised by the use of electric means {(G05D 7/005 takes precedence)}
7/0605	• {specially adapted for solid materials}
7/0611	 . {characterised by the set value given to the control element}
7/0617	• • {specially adapted for fluid materials}
7/0623	{characterised by the set value given to the
	control element}

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7/0629	• • {characterised by the type of regulator means}
7/0635	• • • {by action on throttling means
	(<u>G05D 7/0688</u> , <u>G05D 7/0694</u> take
	precedence)}
7/0641	• • • • {using a plurality of throttling means
	(G05D 7/067 takes precedence)}
7/0647	•••• {the plurality of throttling means being
	arranged in series}
7/0652	••••• {the plurality of throttling means being arranged in parallel}
7/0658	••••• {the plurality of throttling means being
	arranged for the control of a single flow
	from a plurality of converging flows
	(G05D 7/0652 takes precedence; ratio
	control <u>G05D 11/13</u>)}
7/0664	••••• {the plurality of throttling means being
	arranged for the control of a plurality
	of diverging flows from a single flow
	(G05D 7/0652 takes precedence; ratio
	control <u>G05D 11/13</u>)}
7/067	{characterised by free surface flow
	(open channel water distribution systems
	<u>E02B 13/00</u>)}
7/0676	• • • • {by action on flow sources ($\underline{G05D7}/0688$,
- 10 - 20 -	<u>G05D 7/0694</u> take precedence)}
7/0682	• • • • {using a plurality of flow sources}
7/0688	• • • • {by combined action on throttling means
	and flow sources (<u>G05D 7/0694</u> takes
7/0/04	precedence)}
7/0694	•••• {by action on throttling means or flow sources of very small size, e.g. microfluidics
	(microvalves <u>F16K 99/0001</u> ; microstructural
	devices per se B81B)}
	devices <u>per se B81B</u>)}
9/00	Level control, e.g. controlling quantity of material
	Level control, e.g. controlling quantity of material stored in vessel
9/02	Level control, e.g. controlling quantity of material stored in vessel . without auxiliary power
9/02 9/04	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power
9/02	Level control, e.g. controlling quantity of material stored in vessel . without auxiliary power
9/02 9/04	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means
9/02 9/04 9/12	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical
9/02 9/04 9/12	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means
9/02 9/04 9/12	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-
9/02 9/04 9/12	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, <u>G05D 21/00</u>; control of humidity <u>G05D 22/00</u>;
9/02 9/04 9/12	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, <u>G05D 21/00</u>; control of humidity <u>G05D 22/00</u>; control of temperature by varying the mixing ratio of
9/02 9/04 9/12	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, <u>G05D 21/00</u>; control of humidity <u>G05D 22/00</u>; control of temperature by varying the mixing ratio of two fluids having different temperatures <u>G05D 23/13</u>;
9/02 9/04 9/12 11/00	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00)
9/02 9/04 9/12 11/00	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action}
9/02 9/04 9/12 11/00 11/001 11/003	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, <u>G05D 21/00</u>; control of humidity <u>G05D 22/00</u>; control of temperature by varying the mixing ratio of two fluids having different temperatures <u>G05D 23/13</u>; control of viscosity <u>G05D 24/00</u>) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps}
9/02 9/04 9/12 11/00 11/001 11/003 11/005	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps}
9/02 9/04 9/12 11/00 11/001 11/003 11/005	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid}
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, <u>G05D 21/00</u>; control of humidity <u>G05D 22/00</u>; control of temperature by varying the mixing ratio of two fluids having different temperatures <u>G05D 23/13</u>; control of viscosity <u>G05D 24/00</u>) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor}
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/008 11/008 11/02	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006 11/008 11/02 11/03	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power with auxiliary non-electric power
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006 11/008 11/02 11/03 11/035	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006 11/008 11/02 11/03 11/035	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power with auxiliary non-electric power by sensing weight of individual components, e.g. gravimetric procedure
9/02 9/04 9/12 11/00 11/00 11/003 11/005 11/006 11/008 11/02 11/03 11/035 11/04	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, <u>G05D 21/00</u>; control of humidity <u>G05D 22/00</u>; control of temperature by varying the mixing ratio of two fluids having different temperatures <u>G05D 23/13</u>; control of viscosity <u>G05D 24/00</u>) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power with auxiliary non-electric power by sensing weight of individual components,
9/02 9/04 9/12 11/00 11/00 11/003 11/005 11/006 11/008 11/02 11/03 11/035 11/04	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power with auxiliary non-electric power by sensing weight of individual components, e.g. gravimetric procedure by sensing density of mixture, e.g. using aerometer
9/02 9/04 9/12 11/00 11/00 11/003 11/005 11/006 11/008 11/02 11/03 11/035 11/04 11/06	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power with auxiliary non-electric power by sensing weight of individual components, e.g. gravimetric procedure by sensing density of mixture, e.g. using
9/02 9/04 9/12 11/00 11/00 11/003 11/005 11/006 11/008 11/02 11/03 11/035 11/04 11/06	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power by sensing weight of individual components, e.g. gravimetric procedure by sensing density of mixture, e.g. using aerometer by sensing concentration of mixture, e.g.
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006 11/008 11/02 11/03 11/035 11/04 11/06 11/08	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power by sensing weight of individual components, e.g. gravimetric procedure by sensing density of mixture, e.g. using aerometer by sensing concentration of mixture, e.g. measuring pH value
9/02 9/04 9/12 11/00 11/001 11/003 11/005 11/006 11/008 11/02 11/03 11/04 11/06 11/08 11/08	 Level control, e.g. controlling quantity of material stored in vessel without auxiliary power with auxiliary non-electric power characterised by the use of electric means Control of flow ratio (control of chemical or physico-chemical variables, e.g. pH-value, G05D 21/00; control of humidity G05D 22/00; control of temperature by varying the mixing ratio of two fluids having different temperatures G05D 23/13; control of viscosity G05D 24/00) {with discontinuous action} {using interconnected flow control elements} {using synchronised pumps} {involving a first fluid acting on the feeding of a second fluid} {involving a fluid operating a pump motor} Controlling ratio of two or more flows of fluid or fluent material without auxiliary power with auxiliary non-electric power by sensing weight of individual components, e.g. gravimetric procedure by sensing density of mixture, e.g. using aerometer by sensing concentration of mixture, e.g. measuring pH value w sensing moisture of non-aqueous liquids

11/131	• • {by measuring the values related to the quantity of the individual components (<u>G05D 11/139</u> takes precedence)}
11/132	 . • {by controlling the flow of the individual components (<u>G05D 11/133</u> takes precedence)}
11/133	• • • { with discontinuous action }
11/134	•••• {by sensing the weight of the individual components}
11/135	• • {by sensing at least one property of the mixture (<u>G05D 11/139</u> takes precedence)}
11/136	• • • {by sensing the viscosity}
11/137	• • • {by sensing the density of the mixture}
11/138	• • • {by sensing the concentration of the mixture, e.g. measuring pH value}
11/139	• • • {by measuring a value related to the quantity of the individual components and sensing at least one property of the mixture}
11/16	• Controlling mixing ratio of fluids having different temperatures, e.g. by sensing the temperature of a mixture of fluids having different viscosities
13/00	Control of linear speed; Control of angular speed; Control of acceleration or deceleration, e.g. of a
	prime mover
13/02	• Details
13/04	• providing for emergency tripping of an engine in case of exceeding maximum speed
13/06	• providing for damping of erratic vibrations in governors
13/08	• without auxiliary power
13/10	. Centrifugal governors with fly-weights
13/12	Details
13/14	• • • Fly weights; Mountings thereof; Adjusting equipment for limits, e.g. temporarily
13/16	Risers; Transmission gear therefor; Restoring mechanisms therefor
13/18	counterbalanced by spider springs acting immediately upon the fly-weights
13/20	counterbalanced by spider springs acting upon the articulated riser
13/22	• • • counterbalanced by fluid pressure acting upon the articulated riser
13/24	counterbalanced by two or more different appliances acting simultaneously upon the riser, e.g. with both spring force and fluid pressure or with both spring force and
13/26	fluid pressure or with both spring force and electromagnetic forcewith provision for modulating the degree of
	non-uniformity of speed
13/28	• • • with provision for performing braking effects in case of increased speed
13/30	• Governors characterised by fluid features in which the speed of a shaft is converted into fluid pressure
13/32	using a pump
13/34	• with auxiliary non-electric power
13/36	• using regulating devices with proportional band, i.e. P regulating devices
13/38	 involving centrifugal governors of fly-weight type
13/40	• • • involving fluid governors of pump type

13/42	
	• • involving fluid governors of flow-controller type, i.e. the width of liquid flow being controlled by fly-weights
13/44	involving fluid governors of jet type
13/46	• using regulating devices with proportional band
13/40	and integral action, i.e. PI regulating devices
13/48	• • • involving resilient restoring mechanisms
13/50	• • involving connecting means or superimposing a proportional regulating device and an integral regulating device
13/52	using regulating devices with proportional band and derivative action, i.e. PD regulating devices
13/54	involving centrifugal governors of fly-weight
	type exerting an acceleratory effect
13/56	• • • involving restoring mechanisms exerting a delay effect
13/58	• • • involving means for connecting a speed
	regulating device and an acceleration regulating device
13/60	• • using regulating devices with proportional band,
	derivative and integral action, i.e. PID regulating devices
13/62	• characterised by the use of electric means, e.g.
10, 02	use of a tachometric dynamo, use of a transducer converting an electric value into a displacement
12/64	{(electric motor control $\underline{H02P}$)}
13/64	• Compensating the speed difference between engines meshing by a differential gearing or the
	speed difference between a controlling shaft and a
	controlled shaft { $(\underline{G05D \ 13/62} \text{ takes precedence})$ }
13/66	• Governor units providing for co-operation with
15/00	control dependent upon a variable other than speed
15/00	Control of mechanical force or stress; Control of mechanical pressure
15/00 15/01	
	mechanical pressure
15/01	mechanical pressurecharacterised by the use of electric meansControl of fluid pressure
15/01 16/00	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal
15/01 16/00	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure
15/01 16/00 16/02 16/024	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator}
15/01 16/00 16/02	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure
15/01 16/00 16/02 16/024	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow
15/01 16/00 16/02 16/024 16/028	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)}
15/01 16/00 16/02 16/024 16/028 16/04	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power
15/01 16/00 16/02 16/024 16/028 16/04 16/0402	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series}
15/01 16/00 16/02 16/024 16/028 16/04 16/0402	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows,
15/01 16/00 16/02 16/024 16/028 16/04 16/0402 16/0404	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow
15/01 16/00 16/024 16/028 16/04 16/0402 16/0404 16/060 16/0608	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow path and having slidable elements}
15/01 16/00 16/02 16/024 16/028 16/04 16/0402 16/0404 16/06	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow
15/01 16/00 16/02 16/024 16/028 16/04 16/0402 16/0404 16/060 16/0608	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the sensing element being deformable, e.g. Bourdon tube} { the deformable sensing element acting as a
15/01 16/00 16/02 16/024 16/028 16/0402 16/0404 16/060 16/0608 16/0611	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow path and having slidable elements} { the sensing element being deformable, e.g. Bourdon tube} . { the deformable sensing element acting as a throttling member}
15/01 16/00 16/024 16/028 16/0402 16/0402 16/0404 16/0608 16/0608 16/0611 16/0613 16/0616	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow path and having slidable elements} { the sensing element being deformable, e.g. Bourdon tube} . { the deformable sensing element acting as a throttling member} { the sensing element being a bellow}
15/01 16/00 16/024 16/028 16/0402 16/0404 16/060 16/0608 16/0611 16/0613	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow path and having slidable elements} { the sensing element being deformable, e.g. Bourdon tube} { the deformable sensing element acting as a throttling member} { the sensing element being a bellow} { the sensing element being a bellow}
15/01 16/00 16/02 16/024 16/028 16/0404 16/0402 16/0404 16/0608 16/0611 16/0613 16/0616 16/0619	 mechanical pressure characterised by the use of electric means Control of fluid pressure Modifications to reduce the effects of instability, e.g. due to vibrations, friction, abnormal temperature, overloading or imbalance {Controlling the inlet pressure, e.g. back-pressure regulator} {Controlling a pressure difference (control of flow G05D 7/00)} without auxiliary power {with two or more controllers mounted in series} {with two or more controllers mounted in parallel} the sensing element being a flexible membrane, yielding to pressure, e.g. diaphragm, bellows, capsule { the controller being mounted within the flow path and having slidable elements} { the sensing element being deformable, e.g. Bourdon tube} . { the deformable sensing element acting as a throttling member} { the sensing element being a bellow} { the sensing element being a bellow}

16/0627	• • • • {characterised by the form of the obturator}
16/063	• • {the sensing element being a membrane}
16/0633	{characterised by the properties of the
	membrane }
16/0636	\ldots {characterised by the loading device of the
	membrane, e.g. spring}
16/0638	{characterised by the form of the obturator}
16/0641	• • • • { the obturator is a membrane }
16/0644	• • • { the membrane acting directly on the
16/0617	obturator}
16/0647 16/065	 {using one membrane without spring} {characterised by the form of the
10/005	obturator}
16/0652	• • • • {using several membranes without spring}
16/0655	• • • • {using one spring-loaded membrane}
16/0658	••••• {characterised by the form of the
	obturator}
16/0661	• • • • • {characterised by the loading
	mechanisms of the membrane}
16/0663	• • • • {using a spring-loaded membrane with a
16/0666	spring-loaded slideable obturator}
16/0666	obturator}
16/0669	• • • • • {characterised by the loading
10,000,	mechanisms of the membrane}
16/0672	{using several spring-loaded membranes}
16/0675	• • • { the membrane acting on the obturator
	through a lever}
16/0677	• • • • {using one membrane without spring}
16/068	{characterised by the form of the
16/0683	obturator}
16/0686	• • • • • {using a spring-roaded memorate}
16/0688	{characterised by the form of the
10/0000	obturator}
16/0691	{characterised by the loading
	mechanisms of the membrane}
16/0694	•••• {using a spring-loaded membrane with a
1 6/0 60 7	spring-loaded slideable obturator}
16/0697	{using several membranes}
16/08	Control of liquid pressure
16/10	• the sensing element being a piston or plunger
16/101	• • • {the controller being arranged as a multiple- way valve}
16/103	• • { the sensing element placed between the inlet
	and outlet (multiple-way valve <u>G05D 16/101</u>)}
16/106	{Sleeve-like sensing elements; Sensing
	elements surrounded by the flow path}
16/107	• • • {with a spring-loaded piston in combination
	with a spring-loaded slideable obturator that
	move together over range of motion during normal operation}
16/109	• • • { with two or more pistons acting as a single
-	pressure controller that move together over
	range of motion during normal operations
	(controllers mounted in series <u>G05D 16/0402</u> ,
16/12	controller mounted in parallel <u>G05D 16/0404</u>)}
16/12 16/14	the sensing element being a floatwith auxiliary non-electric power
16/14 16/16	 with auxiliary non-electric power derived from the controlled fluid
16/16	 {using membranes within the main valve}
16/165	 . {using pistons within the main valve} . {using pistons within the main valve}
10/100	• • • [using pistons within the main varve]

16/18	derived from an external source
16/185	• • • {using membranes within the main valve}
16/187	• • { using pistons within the main valve }
16/20	characterised by the use of electric means
16/2006	• • {with direct action of electric energy on
	controlling means (combination of electric and non-electric auxiliary <u>G05D 16/2093</u>)}
16/2013	• • • {using throttling means as controlling means}
16/202	• • • { actuated by an electric motor }
16/2022	{actuated by a proportional solenoid
	(throttling means <u>G05D 16/2024</u>)}
16/2024	• • • • {the throttling means being a multiple-way valve}
16/2026	• • • • {with a plurality of throttling means}
16/2033	•••• {the plurality of throttling means being
	arranged in series}
16/204	••••• {the plurality of throttling means being arranged in parallel}
16/2046	•••• {the plurality of throttling means
	being arranged for the control of a
	single pressure from a plurality of
	converging pressures (<u>G05D 16/204</u> takes precedence)}
16/2053	• • • • • {the plurality of throttling means
10/2033	comprising only a first throttling means
	acting on a higher pressure and a second
	throttling means acting on a lower
	pressure, e.g. the atmosphere}
16/206	•••• {the plurality of throttling means being
	arranged for the control of a plurality of
	diverging pressures from a single pressure (G05D 16/204 takes precedence)}
16/2066	• • {using controlling means acting on the pressure
10/2000	source}
16/2073	•••• {with a plurality of pressure sources}
16/208	• • • {using a combination of controlling means as
	defined in G05D 16/2013 and G05D 16/2066
	$(\underline{G05D \ 16/2073} \text{ takes precedence})\}$
16/2086	• • {without direct action of electric energy on the
	controlling means (combination of electric and
16/2093	 non-electric auxiliary <u>G05D 16/2093</u>)} • {with combination of electric and non-electric
10/2075	auxiliary power}
16/2095	• • • {using membranes within the main valve}
16/2097	• • • {using pistons within the main valve}
17/00	Control of torque; Control of mechanical power
17/02	• characterised by the use of electric means
19/00	Control of mechanical oscillations, e.g. of
19/02	amplitude, of frequency, of phasecharacterised by the use of electric means
21/00	Control of chemical or physico-chemical variables,
21/00	e.g. pH value
21/02	• characterised by the use of electric means
22/00	Control of humidity
22/02	• characterised by the use of electric means
23/00	Control of temperature
	NOTE
	In groups <u>G05D 23/01</u> - <u>G05D 23/32</u> , the
	last place priority rule is applied, i.e. at each
	hierarchical level in the absence of an indication

hierarchical level, in the absence of an indication

G05D 23/00 (continued)	to the contrary, classification is made in the last appropriate place.
23/01	• without auxiliary power
	• •
23/015	• • {with mechanical sensing element not covered by
	groups <u>G05D 23/02</u> and <u>G05D 23/12</u> }
23/02	• • with sensing element expanding and contracting in response to changes of temperature
	(G05D 23/13 takes precedence)
23/021	• • • {the sensing element being a non-metallic
	solid, e.g. elastomer, paste}
23/022	• • • {the sensing element being placed within a regulating fluid flow}
23/023	• • • { the sensing element being placed outside a regulating fluid flow}
23/024	• • { the sensing element being of the rod type, tube
	type, or of a similar type}
23/025	• • • { the sensing element being placed within a regulating fluid flow }
23/026	• • • • { the sensing element being placed outside a
	regulating fluid flow}
23/027	• • • • {for combustible fluid}
23/028	• • • {with fusing sensing element}
23/08	• • • with bimetallic element
23/10	• • • • with snap-action elements
23/12	• • with sensing element responsive to pressure or
	volume changes in a confined fluid
23/121	• • {characterised by the sensing element}
23/122	• • • • {using a plurality of sensing elements}
23/123	• • • {the sensing element being placed within a
	regulating fluid flow}
23/125	• • • {the sensing element being placed outside a
22/12/	regulating fluid flow}
23/126	• • • {using a capillary tube}
23/127	• • • • {to control a gaseous fluid circulation}
23/128	••••• {the fluid being combustible}
23/13	• by varying the mixing ratio of two fluids having different temperatures
23/1306	• • { for liquids (<u>G05D 23/1393</u> takes precedence) }
23/1313	• • • • {without temperature sensing element}
23/132	• • • { with temperature sensing element }
23/1326	• • • • {details of the sensor}
23/1333	•••• {measuring the temperature of incoming
	fluid }
23/134	••••• {measuring the temperature of mixed fluid}
23/1346	••••• { with manual temperature setting means }
23/1353	••••• {combined with flow controlling
02/125	means}
23/136	• • • • • {with pressure equalizing means}
23/1366	••••• {using a plurality of sensing elements}
23/1373	••••• { measuring the temperature of mixed fluid }
23/138	• • • {for gases ($\underline{G05D \ 23/1393}$ takes precedence)}
23/1386	• • { for steam and liquid (<u>G05D 23/1393</u> takes precedence) }
23/1393	• • {characterised by the use of electric means}
23/185	 with auxiliary non-electric power
23/1852	 • (with sensing element expanding and contracting
	in response to change of temperature}
23/1854	• • {with bimetallic element}
23/1856	• • {with sensing element responsive to pressure or
	volume change in a confined fluid}

23/1858	• • {by varying the mixing ratio of fluids having
	different temperatures }
23/19	• characterised by the use of electric means
	$\{(\underline{G05D \ 23/1393} \text{ takes precedence})\}$
23/1902	• {characterised by the use of a variable reference
22/1004	value}
23/1904	• • {variable in time}
23/1905	{associated with tele control}
23/1906 23/1909	 . {using an analogue comparing device} . {whose output amplitude can only take two
23/1909	• • {whose output amplitude can only take two discrete values}
23/1912	• • • {whose output amplitude can take more than
20/1/12	two discrete values}
23/1913	• • {delivering a series of pulses}
23/1917	• {using digital means}
23/1919	• {characterised by the type of controller}
23/192	• • • {using a modification of the thermal impedance
	between a source and the load}
23/1921	• • • {using a thermal motor}
23/1923	• • • {using thermal energy, the cost of which varies
	in function of time}
23/1924	• • • {using thermal energy, the availability of which
	is aleatory}
23/1925	• • {using a combination of auxiliary electric and
00/1007	non-electric power}
23/1927	• {using a plurality of sensors $(\underline{G05D 23}/\underline{1902}, C05D 23/\underline{1017}, and C05D 23/\underline{1010}$ take
	<u>G05D 23/1917</u> , and <u>G05D 23/1919</u> take precedence)}
23/1928	• • {sensing the temperature of one space}
23/1920	 (sensing the temperature of one space) (sensing the temperature in different places in
25/175	thermal relationship with one or more spaces }
23/1931	• • • {to control the temperature of one space}
23/1932	• • • {to control the temperature of a plurality of
	spaces }
23/1934	{each space being provided with one
	sensor acting on one or more control
	means}
23/1935	• • • {using sequential control}
23/1951	• • {with control of the working time of a
22/20	temperature controlling device}
23/20	• with sensing elements having variation of
	electric or magnetic properties with change of temperature (G05D 23/13 takes precedence)
23/2033	• • {details of the sensing element}
23/2033	• • • {the sensing element being a semiconductor}
23/2035	• • • { the sensing element being a ionized gas}
23/2035	• • • • (the sensing element being a dielectric of a
	capacitor}
23/2037	• • • {details of the regulator}
23/2039	• • • {using mechanical means}
23/22	the sensing element being a thermocouple
23/2236	{details of the regulator}
23/2237	••••• {using discharge tubes}
23/2239	• • • • {using photoelectric elements}
23/224	• • • • {using selfs or transformers}
23/24	the sensing element having a resistance varying
	with temperature, e.g. a thermistor
23/2401	• • • • {using a heating element as a sensing
	element}
23/2451	{Details of the regulator}
23/2453	• • • • {using discharge tubes}
23/2454	• • • • • {using photoelectric elements}
23/2456	• • • • • {using selfs or transformers}

23/26	• • • the sensing element having a permeability varying with temperature
23/27	• • with sensing element responsive to radiation
23/275	• • with sensing element expanding, contracting, or fusing in response to changes of temperature
23/27535	• • • {Details of the sensing element}
23/27536	• • • {using fusible material}
23/27537	• • • {using expansible fluid}
23/27539	• • • {using conductible expansible fluid}
23/2754	• • • {using bimetallic element}
23/27541	• • • {using expansible solid}
23/27543	• • • • { using the controlled element as sensing element }
23/30	• Automatic controllers with an auxiliary heating device affecting the sensing element, e.g. for anticipating change of temperature
23/303	• • {using a sensing element having a resistance varying with temperature, e.g. thermistor}
23/306	• • • {using semiconductor devices}
23/32	$\hfill \hfill $
	the auxiliary heating device, e.g. a function of time
24/00	Control of viscosity
24/02	• characterised by the use of electric means
25/00	Control of light, e.g. intensity, colour or phase
	(optical devices or arrangements using movable
	or deformable elements for controlling light
	independent of the light source <u>G02B 26/00</u> ; devices or arrangements, the optical operation of which is
	modified by changing the optical properties of the
	medium of the devices or arrangements for the control
	of light, circuit arrangements specially adapted
	therefor, control of light by electro-magnetic waves,
	electrons or other elementary particles G02F 1/00)
25/02	· characterised by the use of electric means
27/00	Simultaneous control of variables covered by two
	or more of main groups <u>G05D 1/00</u> - <u>G05D 25/00</u>
27/02	• characterised by the use of electric means
20/00	
29/00	Simultaneous control of electric and non-electric variables
00/00	
99/00	Subject matter not provided for in other groups of this subclass
Indexing sche	eme associated with group G05D 1/00
2101/00	Details of software or hardware architectures used
2101/00	for the control of position
	WARNING
	Groups G05D 2101/00 - G05D 2101/26 are
	incomplete pending reclassification of documents
	from groups <u>G05D 1/00</u> – <u>G05D 1/12</u> .
	All groups listed in this Warning should be considered in order to perform a complete search.
2101/10	
2101/10	• using artificial intelligence [AI] techniques
2101/15	• using machine learning, e.g. neural networks
2101/20	• using external object recognition
2101/22	• {using off-board distributed computer resources for
2101/24	performing calculations, e.g. cloud-based}
2101/24	 {decentralised arrangement of the on-board controllers}
	controllers

2101/26	• {retrofitting existing legacy systems}
2103/00	Adaptations for complying with regulatory
	restraints on the operations of the controlled vehicles, e.g. compliance with airspace or traffic
	regulations
	WARNING
	Group $\underline{G05D \ 2103/00}$ is incomplete pending reclassification of documents from groups $\underline{G05D \ 1/00} - \underline{G05D \ 1/12}$.
	All groups listed in this Warning should be considered in order to perform a complete search.
2105/00	Specific applications of the controlled vehicles
	WARNING
	Groups <u>G05D 2105/00</u> - <u>G05D 2105/93</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u> .
	All groups listed in this Warning should be considered in order to perform a complete search.
2105/05	 for soil shifting, building, civil engineering or mining, e.g. excavators
2105/10	• for cleaning, vacuuming or polishing
2105/12	• {for removing ice or snow}
2105/14	• {for collecting waste or trash}
2105/15	• for harvesting, sowing or mowing in agriculture or
2105/17	forestry{for printing, painting or marking}
2105/17	 for transportation
2105/20	• of humans
2105/22	{personal mobility devices}
2105/24	• • • (personal mobility devices)
2105/285	• • {postal packages}
2105/29	• • • {garbage}
2105/30	• for social or care-giving applications
2105/31	• • {for attending to humans or animals, e.g. in health
	care environments}
2105/315	• • {for guiding or for guest attention}
2105/32	• • {for amusement, e.g. toys}
2105/34	• • {for telepresence or videoconferencing}
2105/345	• • {for photography}
2105/35	• for combat
2105/40	• for communications, e.g. wireless network relays
2105/45	• for manufacturing, maintenance or repairing
2105/47	• • {for maintenance or repairing, e.g. fuelling or battery replacement}
2105/50	• for animal husbandry or control, e.g. catching, trapping or scaring of animals
2105/55	 for emergency activities, e.g. search and rescue, traffic accidents or fire fighting
2105/57	• {for producing or harvesting energy}
2105/60	 for sport or gaming activities
2105/65	 for shows or performances
2105/70	 for displaying or announcing information
2105/80	• for information gathering, e.g. for academic
2105/95	research
2105/85	• for patrolling or reconnaissance for police, security or military applications
2105/87	• • {for exploration, e.g. mapping of an area}
2105/89	• • {for inspecting structures, e.g. wind mills,
	bridges, buildings or vehicles}

2107/00 Specific environments of the controlled vehicles WARNING Groups G05D 2107/00 - G05D 2107/95 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. 2107/10 • Outdoor regulated spaces 2107/17 • Spaces reserved for vehicle traffic, e.g. roads, regulated airspace or regulated waters 2107/17 • Spaces with priority for humans, e.g. populated areas, pedestrian ways, parks or beaches 2107/20 • Land use 2107/21 • (Forests) 2107/22 • (Forests) 2107/23 • (Gardens or lawns) 2107/24 • (Sports fields, e.g. golf courses) 2107/27 • (Oceans) 2107/28 • (Rivers) 2107/29 • (Swimming pools) 2107/30 • Off-road 2107/30 • Off-road 2107/40 • Indoor domestic environment 2107/50 • Confined spaces, e.g. tanks, pipelines, tunnels or containers 2107/60 • Open buildings, e.g. offices, hospitals, shopping areas or universities 2107/60 • Offices, universities or schools 2107/61 • (Hospitals)	2105/93	• • {for inventory}
Groups G05D 2107/00 - G05D 2107/95 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. 2107/10 • Outdoor regulated spaces 2107/17 • Spaces reserved for vehicle traffic, e.g. roads, regulated airspace or regulated waters 2107/10 • Spaces reserved for vehicle traffic, e.g. populated areas, pedestrian ways, parks or beaches 2107/20 • Land use 2107/21 • (Forests) 2107/22 • (Forests) 2107/23 • (Gardens or lawns) 2107/24 • (Sports fields, e.g. golf courses) 2107/25 • (Aquatic environments) 2107/26 • (Rivers) 2107/27 • (Catastrophic areas) 2107/30 • Off-road 2107/40 • Indoor domestic environment 2107/50 • Contined spaces, e.g. tanks, pipelines, tunnels or containers 2107/60 • Open buildings, e.g. offices, hospitals, shopping areas or universities 2107/61 • (Shopping areas) 2107/62 • (Griecs, universities or schools) 2107/63 • (Offices, universities or schools) </th <th>2107/00</th> <th>Specific environments of the controlled vehicles</th>	2107/00	Specific environments of the controlled vehicles
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inverted pendulums} 2109/135 {Spherical or cylindrical vehicles; Vehicles with		6
		inverted pendulums}
	2109/135	• {Spherical or cylindrical vehicles; Vehicles with spherical ground-engaging means}

2109/14	• • {moving on a grid}
2109/15	Climbing vehicles
2109/16	• • {Articulated vehicles, e.g. snake-like robots}
2109/18	• • Holonomic vehicles, e.g. with omni wheels
2109/20	Aircraft, e.g. drones
2109/22	• • with fixed wings
2109/23	• • • {Vertical take-off and landing [VTOL] aircraft;
	Short take-off and landing [STOL, STOVL] aircraft}
2109/24	•••• {Convertible aircraft, e.g. tiltrotor aircraft}
2109/25	Rotorcrafts
2109/254	• • • {Flying platforms, e.g. multicopters}
2109/26	• • {Lighter-than-air aircraft}
2109/265	• • {Ornithopters}
2109/27	• • {with flexible wings, e.g. paragliders, kites or
	hang gliders}
2109/28	Missiles
2109/285	• • {Projectiles}
2109/29	• • • {animated with rolling movements}
2109/30	. Water vehicles
2109/34	• • {operating on the water surface}
2109/36	• • • {wind powered, e.g. sailing boats}
2109/38	• • {operating under the water surface, e.g.
	submarines}
2109/40	. Space vehicles
2109/50	• Vehicles specially adapted for two or more of space,
	air, land or water environments, e.g. amphibious vehicles
	venicies
2111/00	Details of signals used for control of position,
	course, altitude or attitude of land, water, air or
	course, altitude or attitude of land, water, air or
	course, altitude or attitude of land, water, air or space vehicles <u>WARNING</u>
	course, altitude or attitude of land, water, air or space vehicles <u>WARNING</u> Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are
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	course, altitude or attitude of land, water, air or space vehicles <u>WARNING</u> Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u> .
	course, altitude or attitude of land, water, air or space vehicles <u>WARNING</u> Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents
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2111/10	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals
2111/10 2111/14	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals}
2111/10 2111/14 2111/17	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals
2111/10 2111/14 2111/17 2111/20	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals Acoustic signals, e.g. ultrasonic signals
2111/10 2111/14 2111/17 2111/20 2111/30	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals Acoustic signals, e.g. ultrasonic signals Radio signals
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2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals} Acoustic signals, e.g. ultrasonic signals Radio signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags}
2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups <u>G05D 2111/00</u> - <u>G05D 2111/67</u> are incomplete pending reclassification of documents from groups <u>G05D 1/00</u> – <u>G05D 1/12</u>. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals} Acoustic signals, e.g. ultrasonic signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags} {generated or reflected by cables or wires
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2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34 2111/36	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals} Acoustic signals, e.g. ultrasonic signals Radio signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags} {generated or reflected by cables or wires carrying current, e.g. boundary wires or leaky feeder cables} Inductive-loop type signals Internal signals, i.e. from sensors located in the
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2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34 2111/36 2111/40	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals Acoustic signals, e.g. ultrasonic signals Radio signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags} {generated or reflected by cables or wires carrying current, e.g. boundary wires or leaky feeder cables} Inductive-loop type signals Internal signals, i.e. from sensors located in the vehicle, e.g. from compasses or angular sensors {generated by inertial navigation means, e.g.
2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34 2111/36 2111/36 2111/40 2111/50	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals} Acoustic signals, e.g. ultrasonic signals Radio signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags} {generated or reflected by cables or wires carrying current, e.g. boundary wires or leaky feeder cables} Inductive-loop type signals Internal signals, i.e. from sensors located in the vehicle, e.g. from compasses or angular sensors {generated by inertial navigation means, e.g. gyroscopes or accelerometers}
2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34 2111/36 2111/36 2111/40 2111/50	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals} Acoustic signals, e.g. ultrasonic signals Radio signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags} {generated or reflected by cables or wires carrying current, e.g. boundary wires or leaky feeder cables} Inductive-loop type signals Internal signals, i.e. from sensors located in the vehicle, e.g. from compasses or angular sensors {generated by inertial navigation means, e.g. gyroscopes or accelerometers} {for measuring the travel distances, e.g. by
2111/10 2111/14 2111/17 2111/20 2111/30 2111/32 2111/34 2111/36 2111/36 2111/40 2111/50 2111/52	 course, altitude or attitude of land, water, air or space vehicles WARNING Groups G05D 2111/00 - G05D 2111/67 are incomplete pending reclassification of documents from groups G05D 1/00 - G05D 1/12. All groups listed in this Warning should be considered in order to perform a complete search. Optical signals {Non-visible signals, e.g. IR or UV signals} {Coherent light, e.g. laser signals} Acoustic signals, e.g. ultrasonic signals Radio signals {transmitted via communication networks, e.g. cellular networks or wireless local area networks [WLAN]} {generated by transmitters powered by energy received from an external transceiver, e.g. generated by passive radio-frequency identification [RFID] tags} {generated or reflected by cables or wires carrying current, e.g. boundary wires or leaky feeder cables} Inductive-loop type signals Internal signals, i.e. from sensors located in the vehicle, e.g. from compasses or angular sensors {generated by inertial navigation means, e.g. gyroscopes or accelerometers}

2111/56	• • {for sensing properties of the surrounding
	medium of the vehicle, e.g. using airspeed
	sensors}
2111/58	• • {for sensing the relative position of different
	elements of a vehicle, e.g. of a steering
	mechanism or of articulated trailers}
2111/60	. Combination of two or more signals
2111/63	• • of the same type, e.g. stereovision or optical flow
2111/64	• • • {taken simultaneously from spaced apart
	sensors, e.g. stereovision}
2111/65	• • • {taken successively, e.g. visual odometry or
	optical flow}
2111/67	Sensor fusion